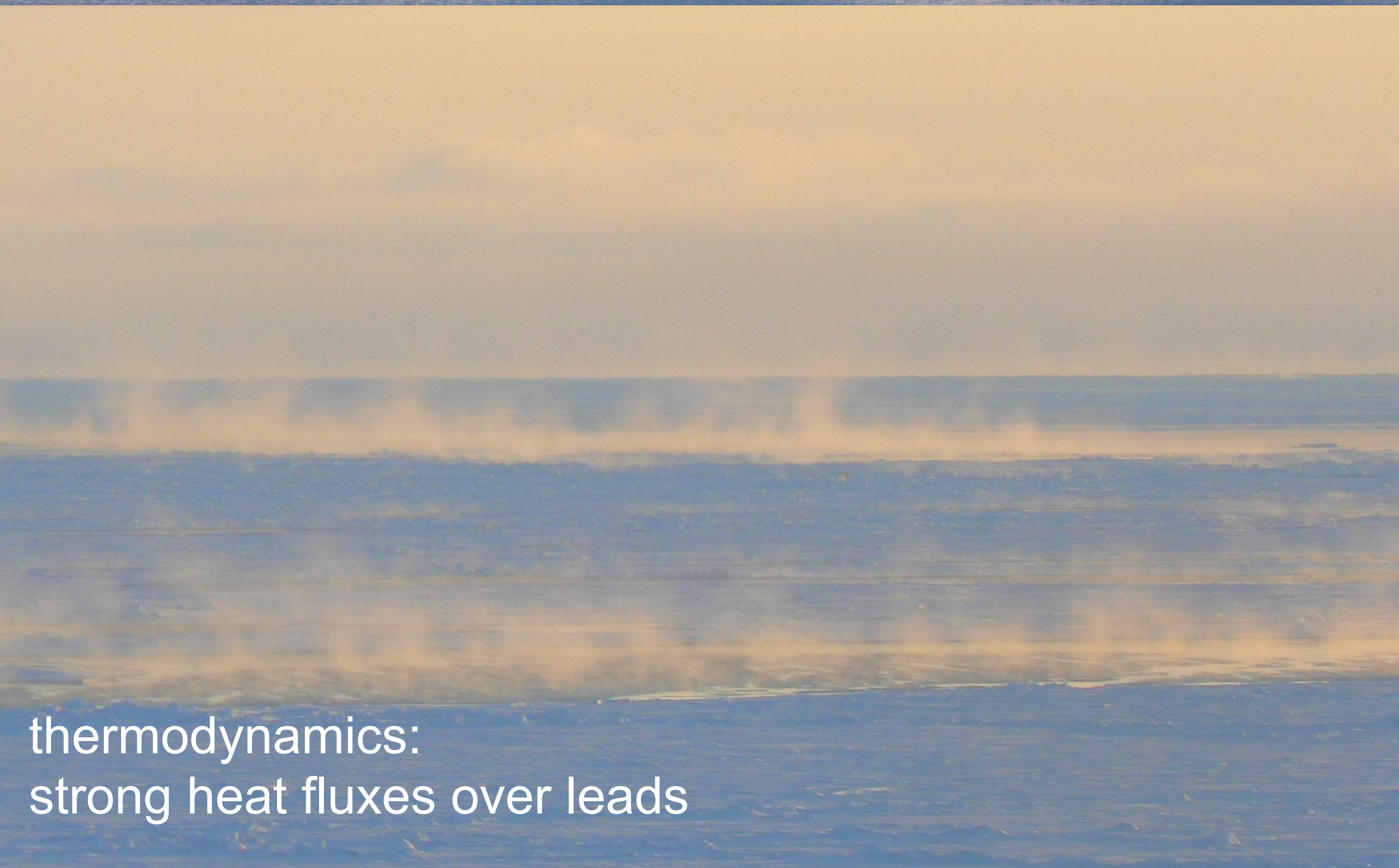


# Introduction to sea ice modelling

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thermodynamics:  
strong heat fluxes over leads



dynamics: ridges and leads, rubble, pack



Photos by M. Hoppmann, S. Hendricks, Ch. Lüpkes



# “Dynamic” duo for Sea Ice



*Dynamics*

*Thermodynamics*

Perovich, 2012, FAMOS



- **(very short) Introduction: Sea ice in the climate system**

- **Thermodynamics**

- heat balance
- heat capacity
- zero-layer, multi-layer models
- salinity, brine, enthalpy
- Snow on ice
- advection
- ice thickness distribution

- **Dynamics**

- continuum assumption
- momentum equations
- surface stress
- divergence of internal stress
- rheology, isotropy, anisotropy, Viscous-Plastic, Maxwell-Elasto-Brittle, Mohr-Coulomb
- ice thickness distribution and ridging

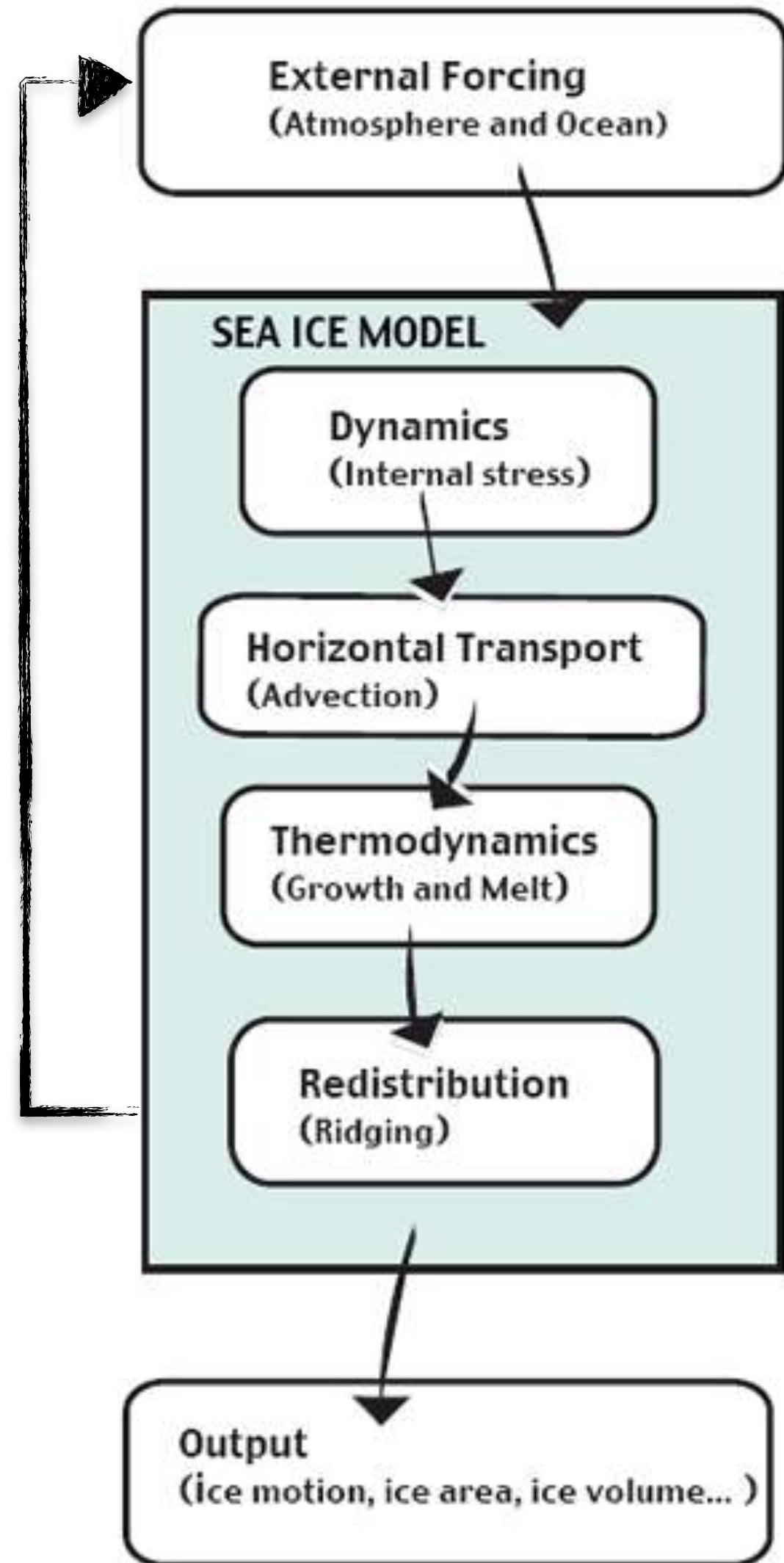
- **Numerical models**

- solution techniques specific to sea-ice models
- implicit solvers
  - Picard/fixed point/FGMRES, JFNK
- explicit solvers:
  - EVP, mEVP, aEVP
  - EAP
- new rheologies
- Discrete Element Models

- **Sea ice models in ECCO -> Ian's talk**

- **Biogeochemistry in sea ice models**

# Sea ice model equations



# thermodynamics: heat balance

- ice-enthalpy includes heat and chemical potential (salinity)

$$\rho \frac{\partial E}{\partial t} = \frac{\partial}{\partial z} \left( \kappa \frac{\partial T}{\partial t} \right) + Q, \quad E(S, T) = c_{p,i}(T + \mu S) - \Lambda (1 - \phi) - c_{p,w} \mu S$$

- often simply:

$$E = c_p T$$

brine fraction



- with boundary conditions

top:

$$\kappa \frac{\partial T}{\partial z} = Q_T \downarrow$$

bottom:

$$T = T_f = T_f(S)$$

$$\rho \Lambda \frac{\partial H}{\partial t} = - \kappa \frac{\partial T}{\partial z} \Big|_{\text{bottom}} - Q_w \uparrow$$

# Stefan's law of ice growth (following Leppäranta, 1993)

- assumptions:

- no thermal inertial:  $E = 0$
- no internal heat source:  $Q = 0$
- no heat flux from ocean:  $Q_w = 0$
- known surface temperature  
 $T_0 = T_0(t)$

$$\rho\Lambda \frac{dH}{dt} = -\kappa \frac{\partial T}{\partial z} = \kappa \frac{T_f - T_0(t)}{H}$$

$$H \frac{dH}{dt} = \frac{1}{2} \frac{dH^2}{dt} dt = \frac{\kappa}{\rho\Lambda} [T_f - T_0(t)]$$

$$\int_0^t \frac{dH^2}{dt} dt' = H(t)^2 - H_0^2 = \frac{2\kappa}{\rho\Lambda} \int_0^t [T_f - T_0(t')] dt'$$

sum of negative degree days

➔ constant temperature profiles (0-layer mode):

$$\frac{\partial T}{\partial z} = \text{constant}$$

$$H(t) = \sqrt{H_0^2 + \frac{2\kappa}{\rho\Lambda} \int_0^t [T_f - T_0(t')] dt'}$$

gives typically 140cm for 180 days of -10K freezing conditions

# Sea ice model equations: “0-layer thermodynamics”



$$\rho \frac{\partial E}{\partial t} = \rho c_p \frac{\partial T}{\partial t} = \frac{\partial}{\partial z} \left( \kappa \frac{\partial T}{\partial t} \right) + Q \quad (\text{Semptner, 1976, 1984})$$

- no internal heat source:  $Q = 0$
- no thermal inertia  $\Rightarrow$  instantaneous temperature adjustment

$$c_p = 0 \Rightarrow \frac{\partial T}{\partial z} = \text{constant} = \frac{T_0 - T_f}{h}$$

- only surface boundary conditions remain:  $\frac{\kappa}{h}(T_0 - T_f) = Q_T \downarrow$
- with  $Q_T \downarrow = Q_{SW\downarrow}(1 - \alpha) + \epsilon Q_{LW\downarrow} - Q_{LW\uparrow}(T_0) + Q_{LH}(T_0) + Q_{SH}(T_0)$

$$\Rightarrow T_0 \Rightarrow Q_T(T_0) \Rightarrow \rho \Lambda \frac{\partial H}{\partial t} = \kappa \frac{T_f - T_0}{H} - Q_w$$



# Sea ice albedo for $Q_{sw\downarrow}(1 - \alpha)$

- simple parameterisations with albedo for ice and snow in freezing (brighter) or melting (darker) conditions
- use melt-pond physics to estimate albedo (e.g., Taylor and Feltham, 2004, Flocco and Feltham, 2007)
- effects of ageing snow and ice, multiple-scattering, absorptive effects of inclusions such as dust and algae (biogeochemistry!)
- important tuning parameter





- snow is a very good insulator:
  - changes surface albedo
  - usually limits shortwave penetration
  - changes vertical diffusion of temperature (from continuity at interface, e.g. Leppäranta, 1991) in 0-layer model:

$$K_{eff} = \frac{K_{ice} K_{snow}}{K_{snow} h_{ice} + K_{ice} h_{snow}}$$

- snow-ice: refreezing of flooded snow on sea ice, especially in Antarctica



- ice-enthalpy

$$\rho \frac{\partial}{\partial t} E = \frac{\partial}{\partial z} \left( \kappa \frac{\partial T}{\partial t} \right) + Q$$

- Simplest model is a three-layer model (two ice layers, one snow layer, e.g. Winton, 2000), more layers (Bitz and Lipscomb, 1999) used CICE/ICEPACK.
- any excess conductive heat flux ( $k\partial T/\partial z$ ) through the ice leads to freezing or melting: change of volume  $S_h (=dh/dt)$
- Hibler (1979): lateral freezing and melting

$$S_c = \frac{1-c}{h_0} \max(S_h, 0) + \frac{c}{2h} \min(S_h, 0)$$

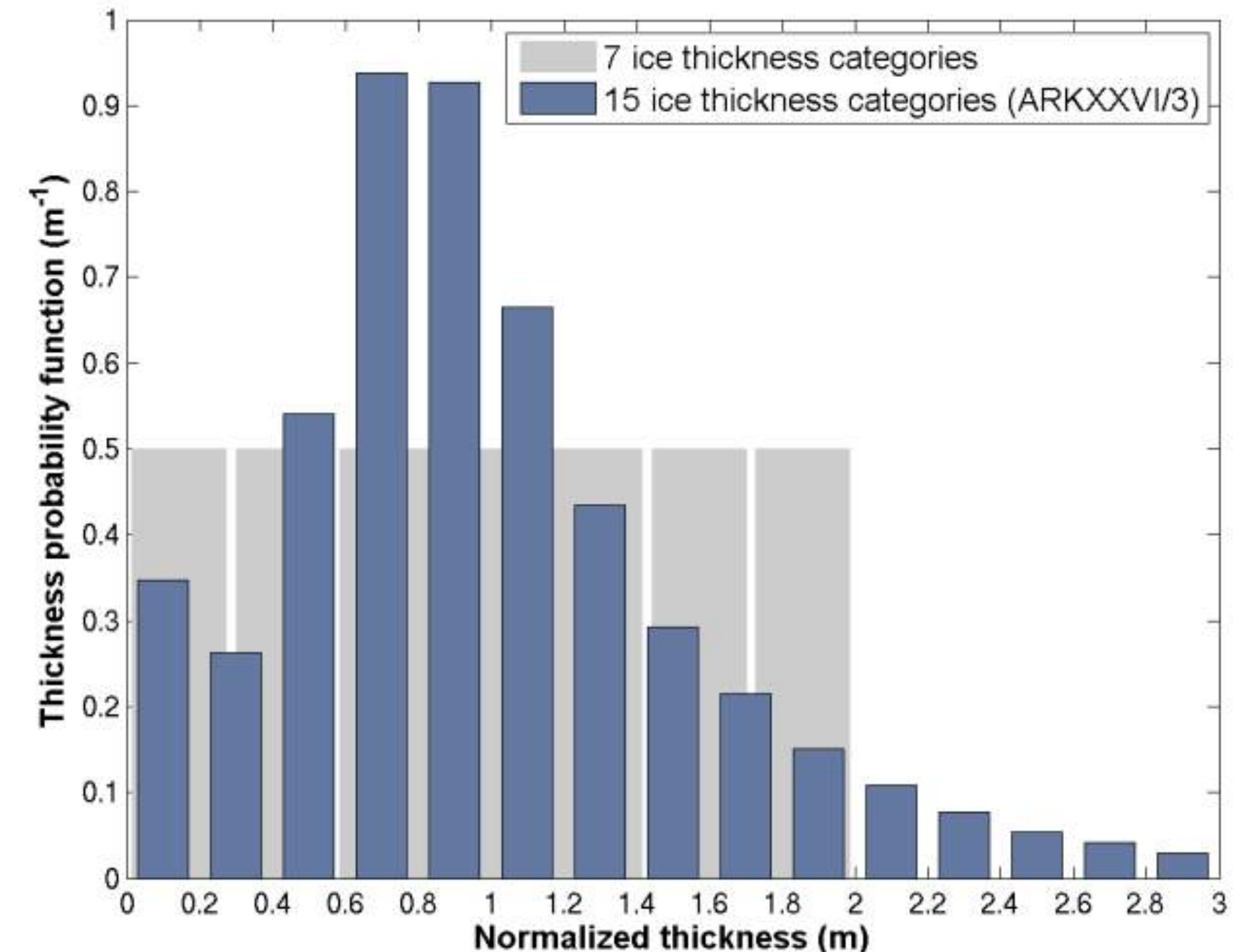
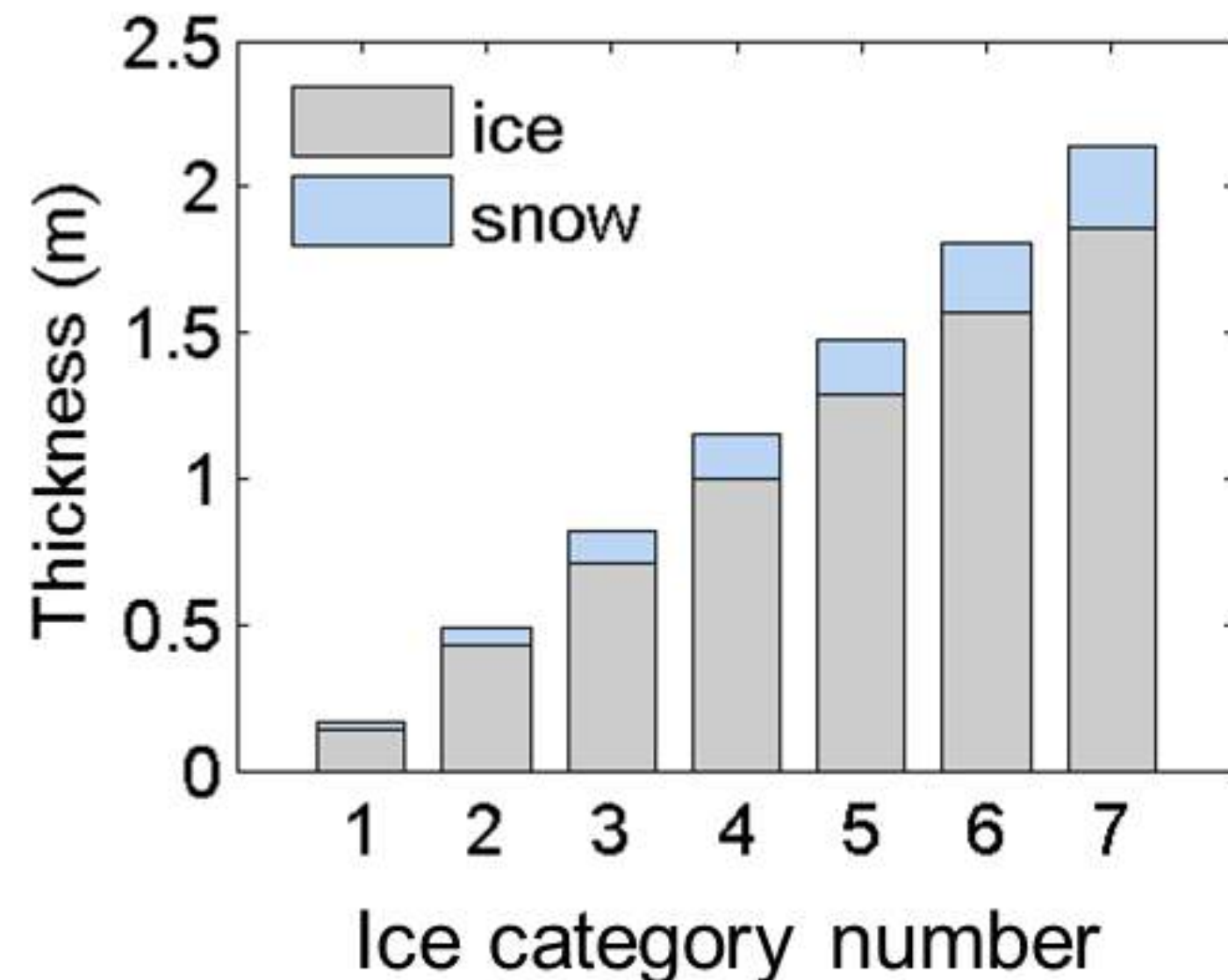
lead closing parameter



# ice thickness distribution (static)

- thick ice (especially with a snow layer) is a good insulator and limits new ice growth
- simple parameterization scales distribution by mean thickness to always allow thin ice

$$Q = (1 - c) Q_0 + c \sum_{k=1}^N Q \left( \frac{2k - 1}{N} \frac{h}{c} \right)$$





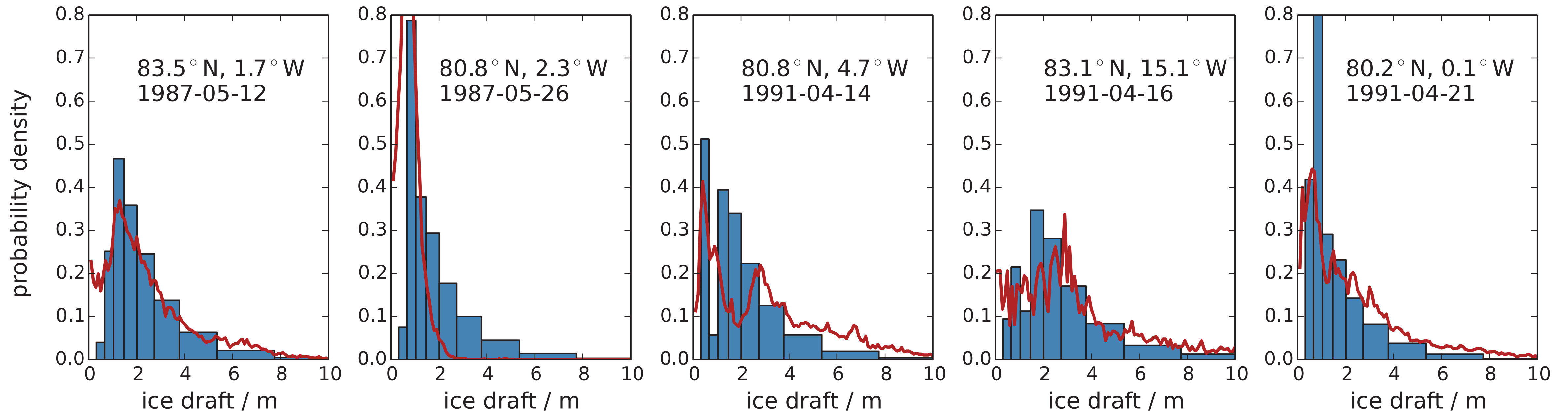
# dynamic ice thickness distribution: redistribution + ridging



- ice concentration equation is replaced by an equation for thickness distribution function  $g(h)$

$$\frac{\partial c}{\partial t} = -\nabla \cdot (c \mathbf{u}) + S_c \longrightarrow \frac{\partial g}{\partial t} = -\nabla \cdot (\mathbf{u} g) - \frac{\partial}{\partial h}(fg) + \Psi$$

ridging function  
+  $\Psi$

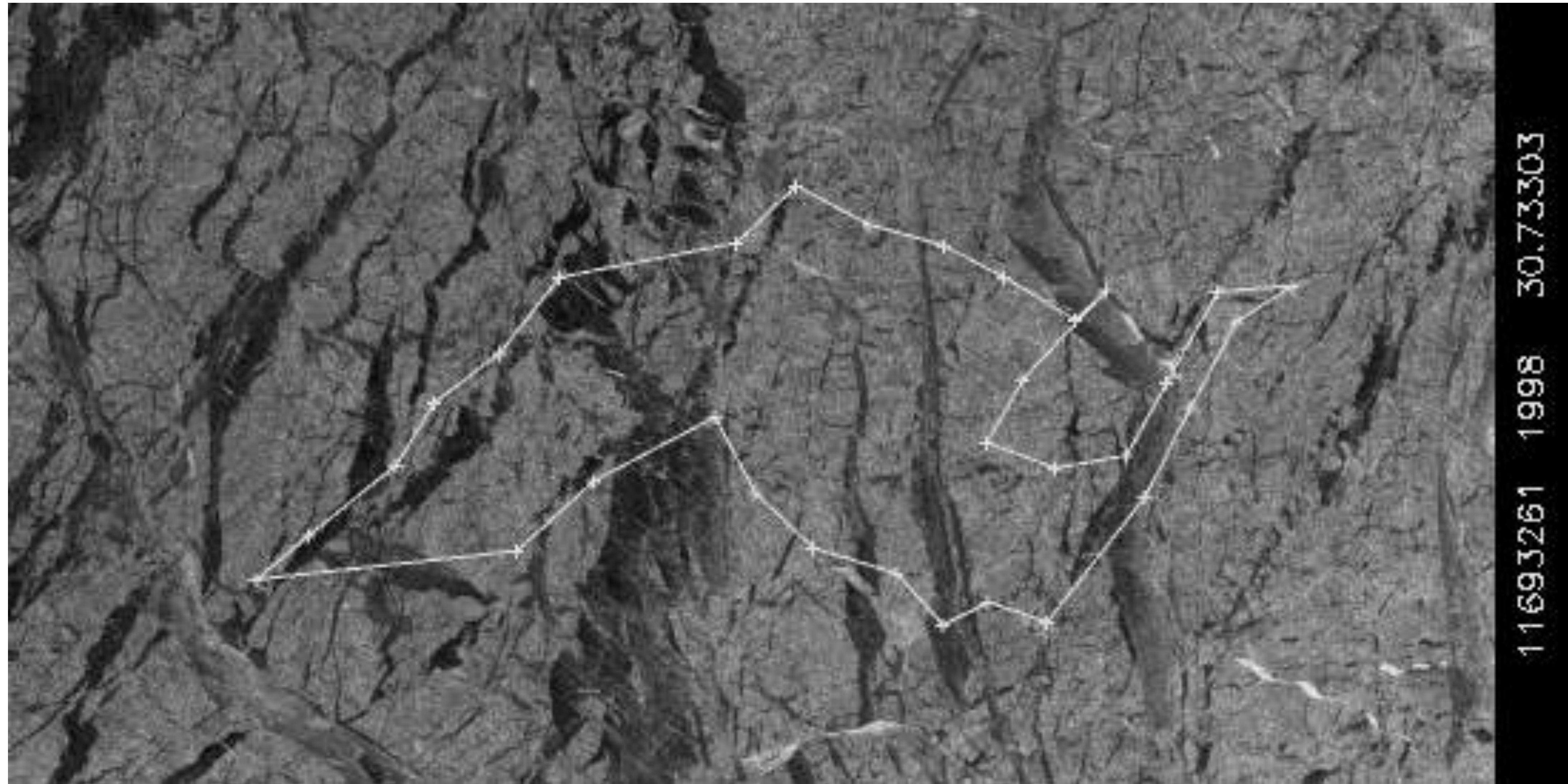


red: observations, blue: model

from Ungermann and Losch (2018)



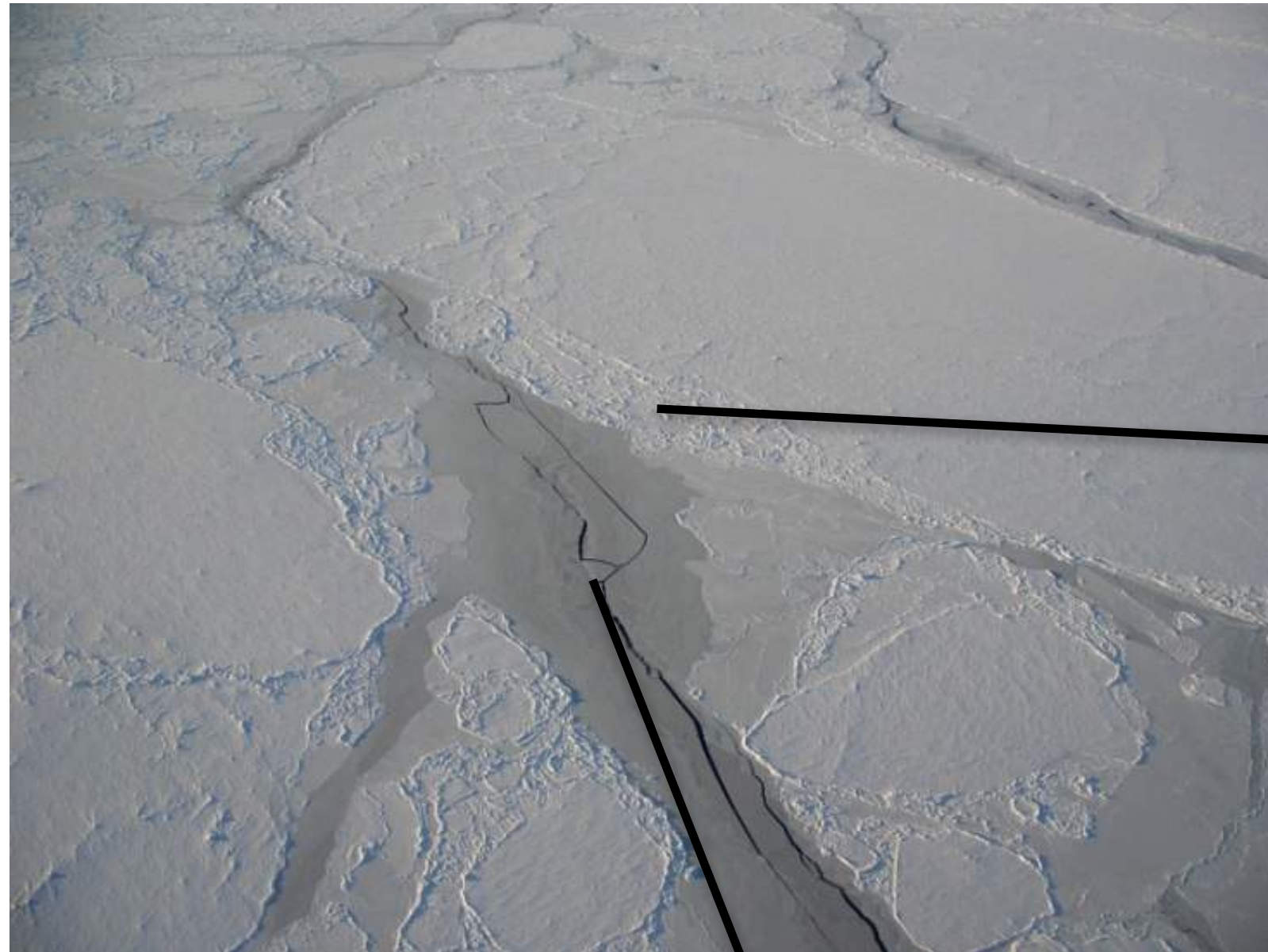
# Dynamics and Deformation



(RGPS data near SHEBA drift station, 1997, R. Kwok)



# Sea Ice Deformation



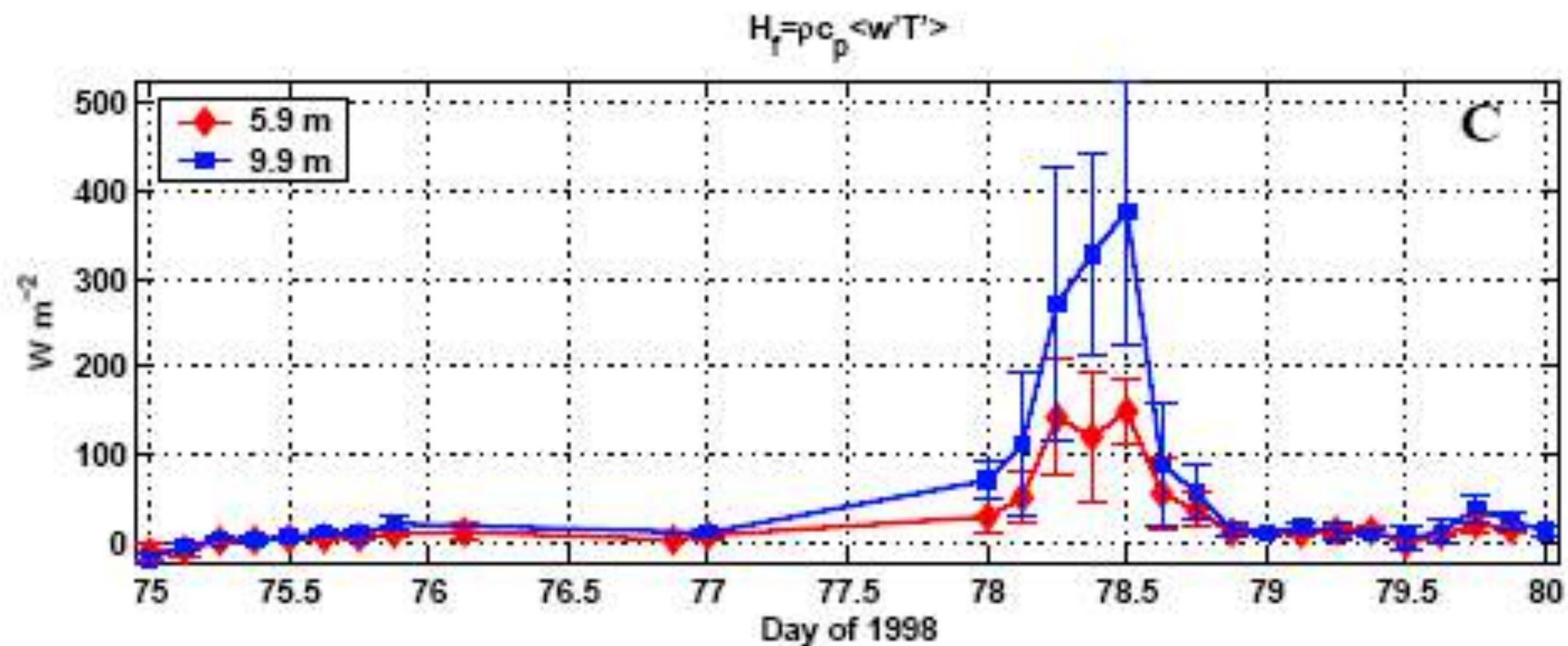
ice compression and shear:  
ridges, rubble fields

breaking ice:  
cracks, leads



# Importance of sea ice deformations

- Affect the thickness distribution through formation of ridges and leads.
- Heat flux through new leads is 1-2 orders of mag higher than over thick ice (Maykut, 1978)
- 25-40% of new ice formation occurs in leads (Kwok, 2006)
- Ridges affect the air-ice and ice-ocean drag
- Ocean upwelling associated to shear



McPhee et al.,  
2005



# Digression: Newtonian Fluid

1. Fluid is continuous + stresses are a linear function of the strain rates
2. Fluid is isotropic
3. In the limit where the strain rates go to zero, the stresses must reduce to the hydrostatic pressure

$$\rho \frac{d\mathbf{u}}{dt} = \nabla \cdot \boldsymbol{\sigma} + R, \quad R = \text{other terms}$$

$$\text{for PE (ocean): } \boldsymbol{\sigma} = \nu \nabla \mathbf{u} - p \Rightarrow \nabla \cdot \boldsymbol{\sigma} = \nabla (\nu \nabla \mathbf{u} - p)$$

$$\text{strain rates } (\nabla \mathbf{u})_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$



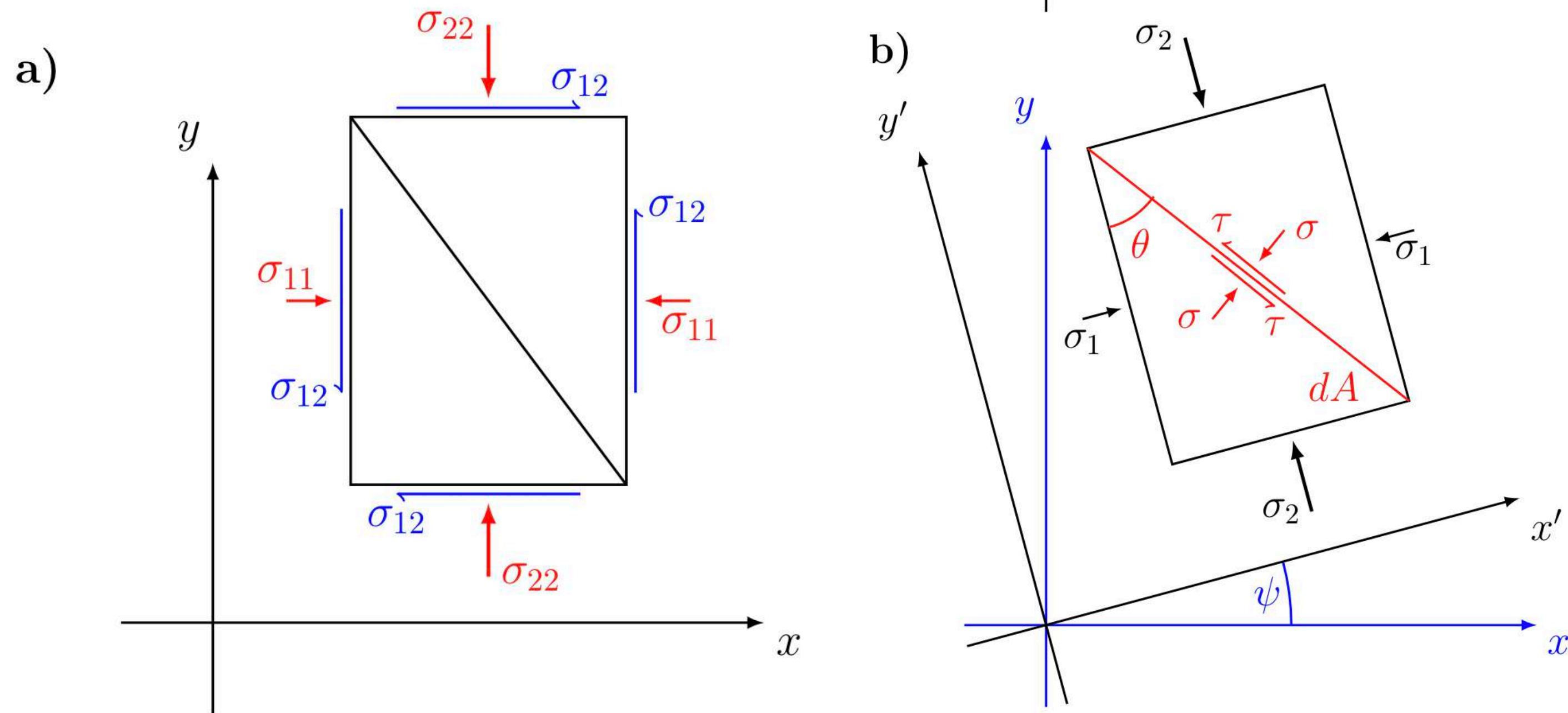
# Sea ice is different (AIDJEX model)



- ensemble of many ice floes with interactions
- continuity assumption at large scales (questionable)
- non-Newtonian (non-normal) fluid (honey vs. mayonnaise)
- strong in compression, weak in tension, intermediate in shear
- elastic response to small perturbations, plastic to large pert.
- => plastic-elastic model (Coon 1974)
- viscous-plastic framework is similar, but numerically simpler (Hibler 1977, 1979), small strain rates lead to viscous creep.
- granular material (like sand: floes = grains) => Mohr-Coulomb law of failure relates shear to normal stress:  $\tau = \mu\sigma + c$



# Stress tensor



$$\sigma = \begin{pmatrix} \sigma_{11} & \sigma_{21} \\ \sigma_{12} & \sigma_{22} \end{pmatrix} = \begin{pmatrix} \sigma_{xx} & \sigma_{yx} \\ \sigma_{xy} & \sigma_{yy} \end{pmatrix} \Rightarrow \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{pmatrix}$$

principle stresses

$$\sigma_{1,2} = \frac{\sigma_{11} + \sigma_{22}}{2} \pm \sqrt{\frac{(\sigma_{11} - \sigma_{22})^2}{4} + \sigma_{12}\sigma_{21}}$$

normal stress  $\sigma$

$$\sigma_I = \frac{1}{2}(\sigma_1 + \sigma_2) = \frac{1}{2}(\sigma_{11} + \sigma_{22})$$

shear stress  $\tau$

$$\sigma_{II} = \frac{1}{2}(\sigma_1 - \sigma_2) = \frac{1}{2}\sqrt{(\sigma_{11} - \sigma_{22})^2 + 4\sigma_{12}\sigma_{21}}$$

- assumption: symmetric  $\Rightarrow \sigma_{21} = \sigma_{12}$
- Mohr-Coulomb law:  $\tau = \mu\sigma + c$  or  $\sigma_{II} = \mu\sigma_I + c/2$



# principal stress plane and yield curve, plastic limit

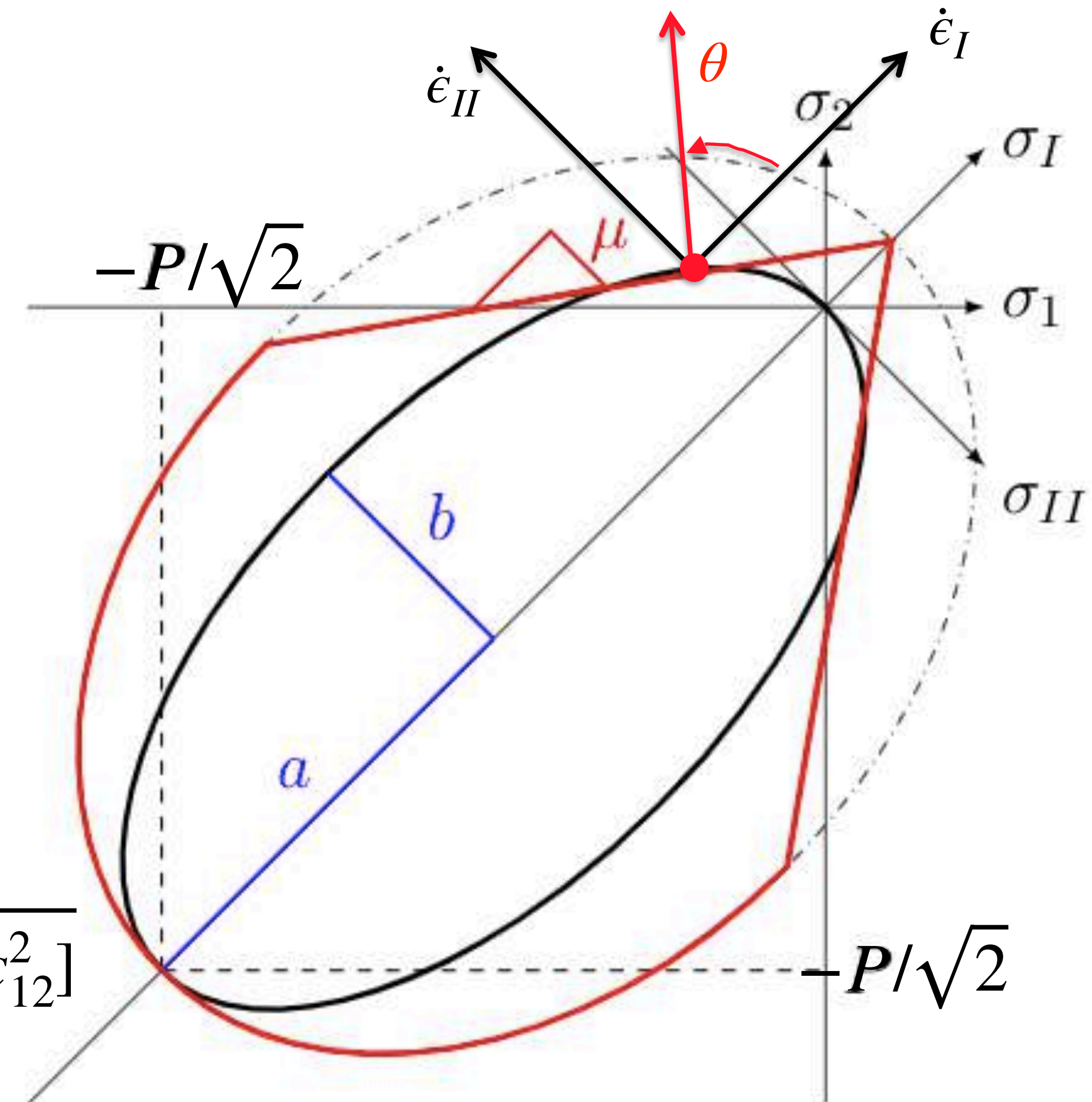
$$\sigma = \begin{pmatrix} \sigma_{11} & \sigma_{21} \\ \sigma_{12} & \sigma_{22} \end{pmatrix} \Rightarrow \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{pmatrix} \Rightarrow \sigma_I \text{ and } \sigma_{II}$$

$$\text{elliptical yield curve: } F = \left( \frac{\sigma_I + P/2}{P/2} \right)^2 + \left( \frac{\sigma_{II}}{P/(2e)} \right)^2 - 1 = 0$$

$$\text{with normal flow rule: } \dot{\epsilon}_{ij} = \lambda \frac{\partial F(\sigma)}{\partial \sigma_{ij}} \quad \left( = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right)$$

$$\Rightarrow \text{constitutive relation: } \sigma_{ij} = 2\eta \dot{\epsilon}_{ij} + \delta_{ij} \left( [\zeta - \eta] \dot{\epsilon}_{kk} - \frac{P}{2} \right)$$

$$e = \frac{a}{b}, \quad \zeta = \frac{P}{2\Delta}, \quad \eta = \frac{\zeta}{e^2}, \quad \Delta = \sqrt{(\dot{\epsilon}_{11} + \dot{\epsilon}_{22})^2 + e^{-2}[(\dot{\epsilon}_{11} - \dot{\epsilon}_{22})^2 + 4\dot{\epsilon}_{12}^2]}$$





# consequence: sea ice dynamics are very non-linear



$$m \frac{\partial \mathbf{u}}{\partial t} = \nabla \cdot \boldsymbol{\sigma} + R, \quad R = \text{other terms}$$

$$\text{with } \sigma_{ij} = \frac{P}{2\Delta} \left\{ 2\dot{\epsilon}_{ij} e^{-2} + [(1 - e^{-2})(\dot{\epsilon}_{11} + \dot{\epsilon}_{22}) - \Delta] \delta_{ij} \right\}$$

with abbreviations

$$\Delta = \sqrt{(\dot{\epsilon}_{11} + \dot{\epsilon}_{22})^2 + e^{-2} [(\dot{\epsilon}_{11} - \dot{\epsilon}_{22})^2 + 4\dot{\epsilon}_{12}^2]}$$

$$\dot{\epsilon}_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \quad (\text{strain rates})$$

$$\longrightarrow m \frac{\partial \mathbf{u}}{\partial t} \propto \frac{\partial}{\partial x_i} \left( \frac{P}{\Delta} \frac{\partial u_i}{\partial x_j} \right) + \text{similar terms}$$

ice strength parametrizations:

$$\text{Hibler (1979): } P = P^* h e^{-C^*(1-c)}$$

$$\text{Rothrock (1975): } P = C_f C_p \int_0^\infty h^2 \omega_r(h) dh$$



- Picard solvers (LSR, Krylov)
- JFNK solver
- EVP solvers: mEVP, aEVP
  
- new MEB rheology
  
- discrete element models (DEM)



$$\mathbf{A}(\mathbf{u}) \cdot \mathbf{u} = \mathbf{b}$$

$$\Rightarrow \text{solve } \mathbf{A}(\mathbf{u}_{n-1}) \cdot \mathbf{u}_n = \mathbf{b}$$

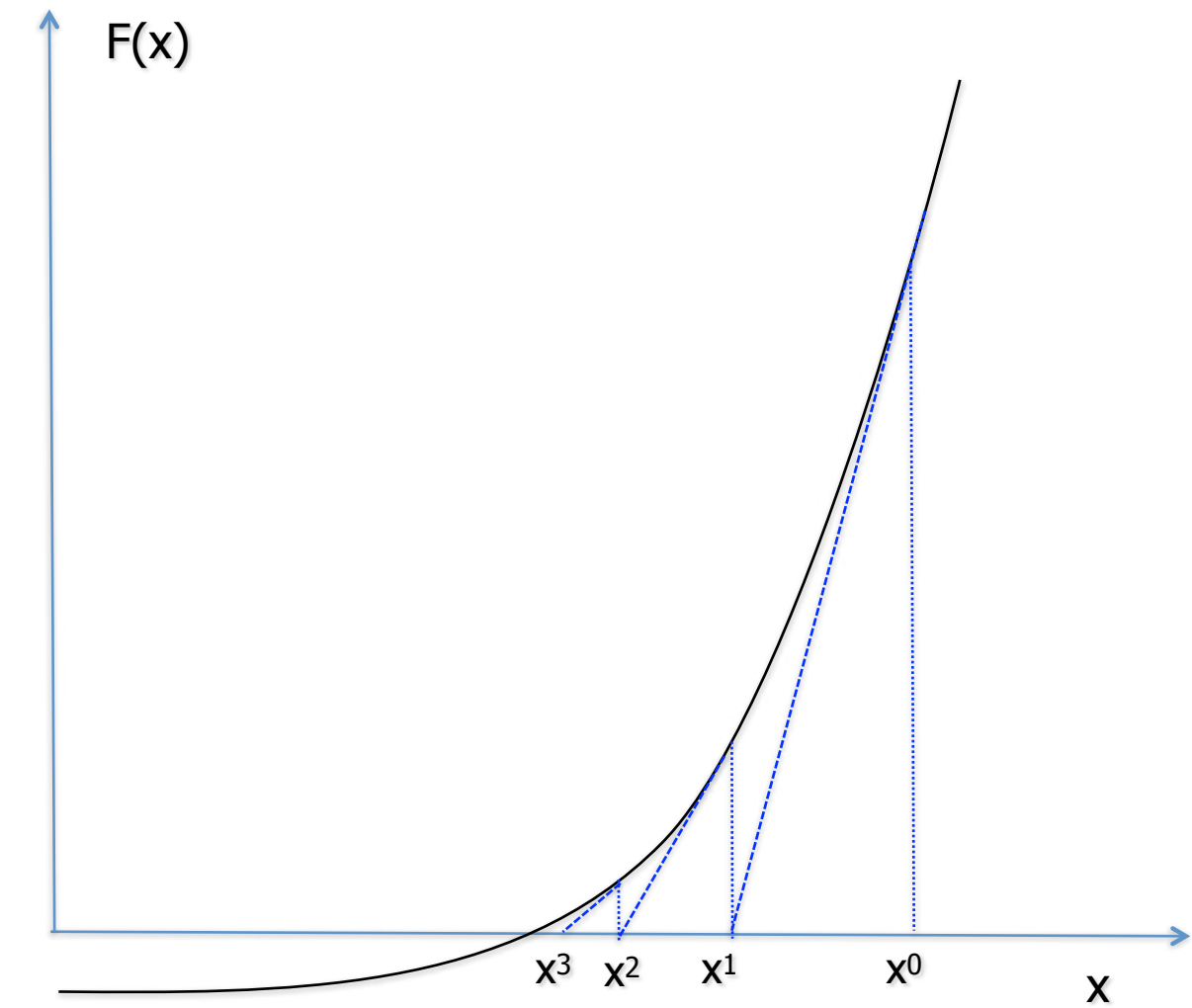
- traditional method, e.g., PSOR, Hübner (1979), LSOR, Zhang and Hübner (1997), (Gauss-Seidel) for linear solver
- Krylov method for linear solver (Lemieux and Tremblay, 2009), requires preconditioner
- stable, but slow

# solution techniques: JFNK solver

$$\mathbf{F}(\mathbf{u}) = \mathbf{A}(\mathbf{u}) \cdot \mathbf{u} - \mathbf{b}$$

$$\mathbf{F}(\mathbf{u}_n) = \mathbf{F}(\mathbf{u}_{n-1}) + \mathbf{F}' \Big|_{\mathbf{u}_{n-1}} \delta \mathbf{u} \stackrel{!}{=} 0$$

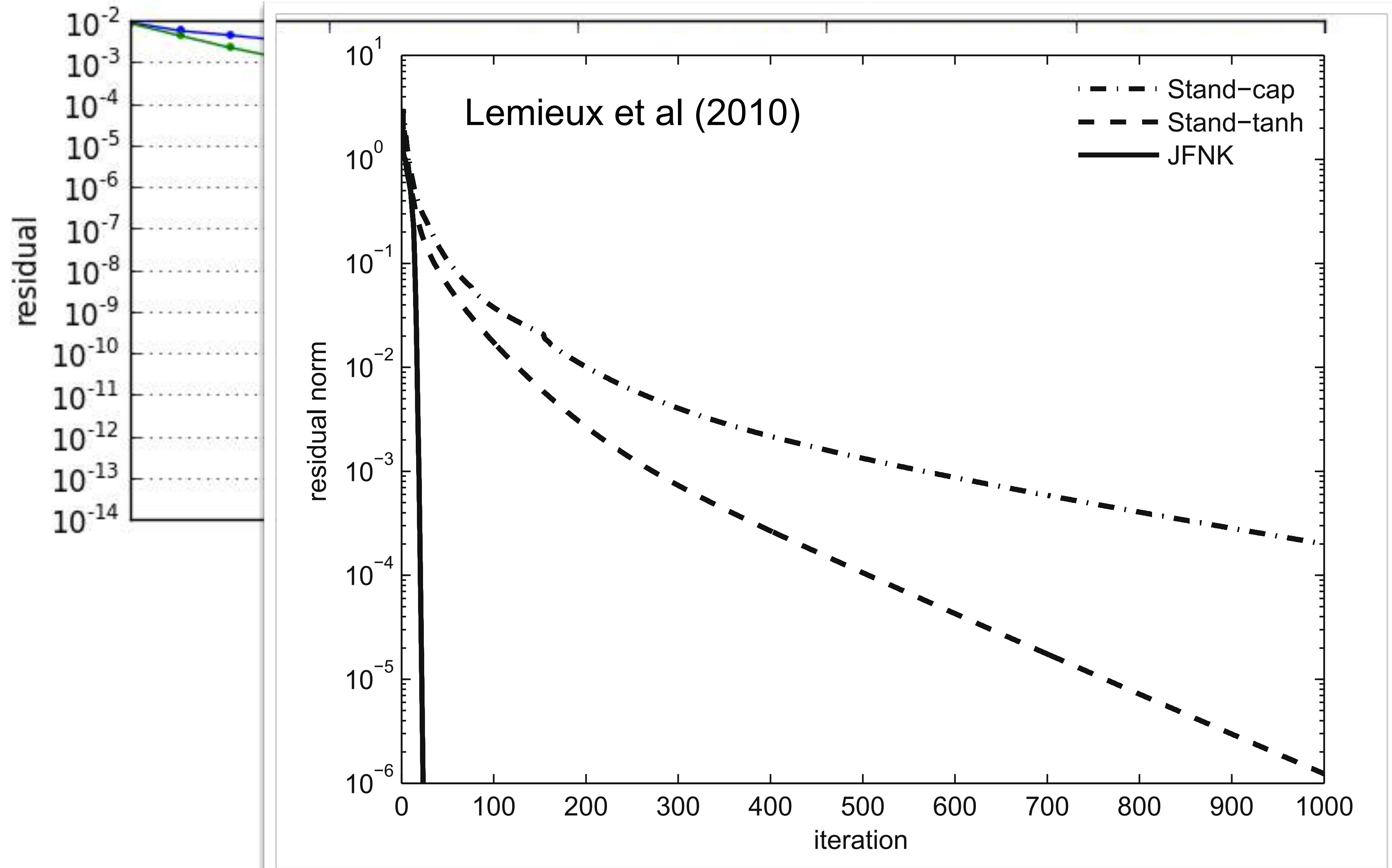
$$\Rightarrow \text{solve} \quad \mathbf{F}'_{n-1} \delta \mathbf{u} = -\mathbf{F}(\mathbf{u}_{n-1}) \quad \Rightarrow \quad \mathbf{u}_n = \mathbf{u}_{n-1} + \delta \mathbf{u}$$



- better (quadratic) convergence near minimum (Lemieux et al. 2010, 2012, Losch et al 2014)
- preconditioner for Krylov solver necessary
- expensive
- unstable, especially at high resolution
- stabilization (e.g. Mehlmann and Richter 2017, involves mixing JFNK and Picard methods)

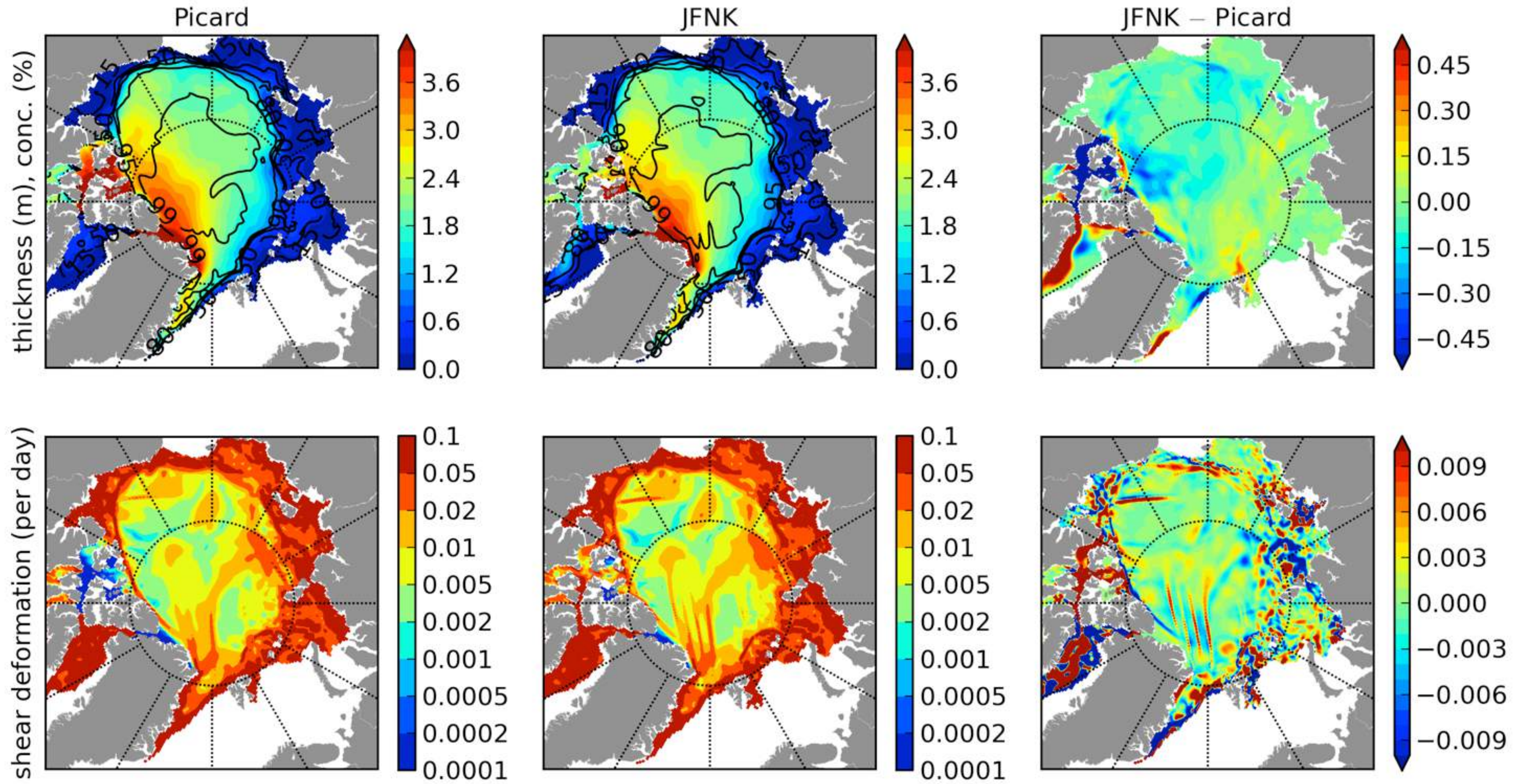


# Picard vs. JFNK





# Does it matter?





$$\sigma_{ij} = \frac{P}{2\Delta} \left\{ 2\dot{\epsilon}_{ij} e^{-2} + [(1 - e^{-2})(\dot{\epsilon}_{11} + \dot{\epsilon}_{22}) - \Delta] \delta_{ij} \right\}$$
$$\Leftrightarrow \frac{\Delta e^2}{P} \sigma_{ij} + \left[ \frac{\Delta(1 - e^2)}{2P} (\sigma_{11} + \sigma_{22}) + \frac{\Delta}{2} \right] \delta_{ij} = \dot{\epsilon}_{ij}$$

- Hunke and Dukowicz (1997)
- does not converge (definitely not to VP, Lemieux et al. 2012, Losch and Danilov 2012)
- adding inertial term to momentum equations fixes convergence (Lemieux et al. 2012, Bouillon et al 2013)
- m(odified)EVP, a(daptive)EVP (Kimmritz et al 2015, 2016, 2017)

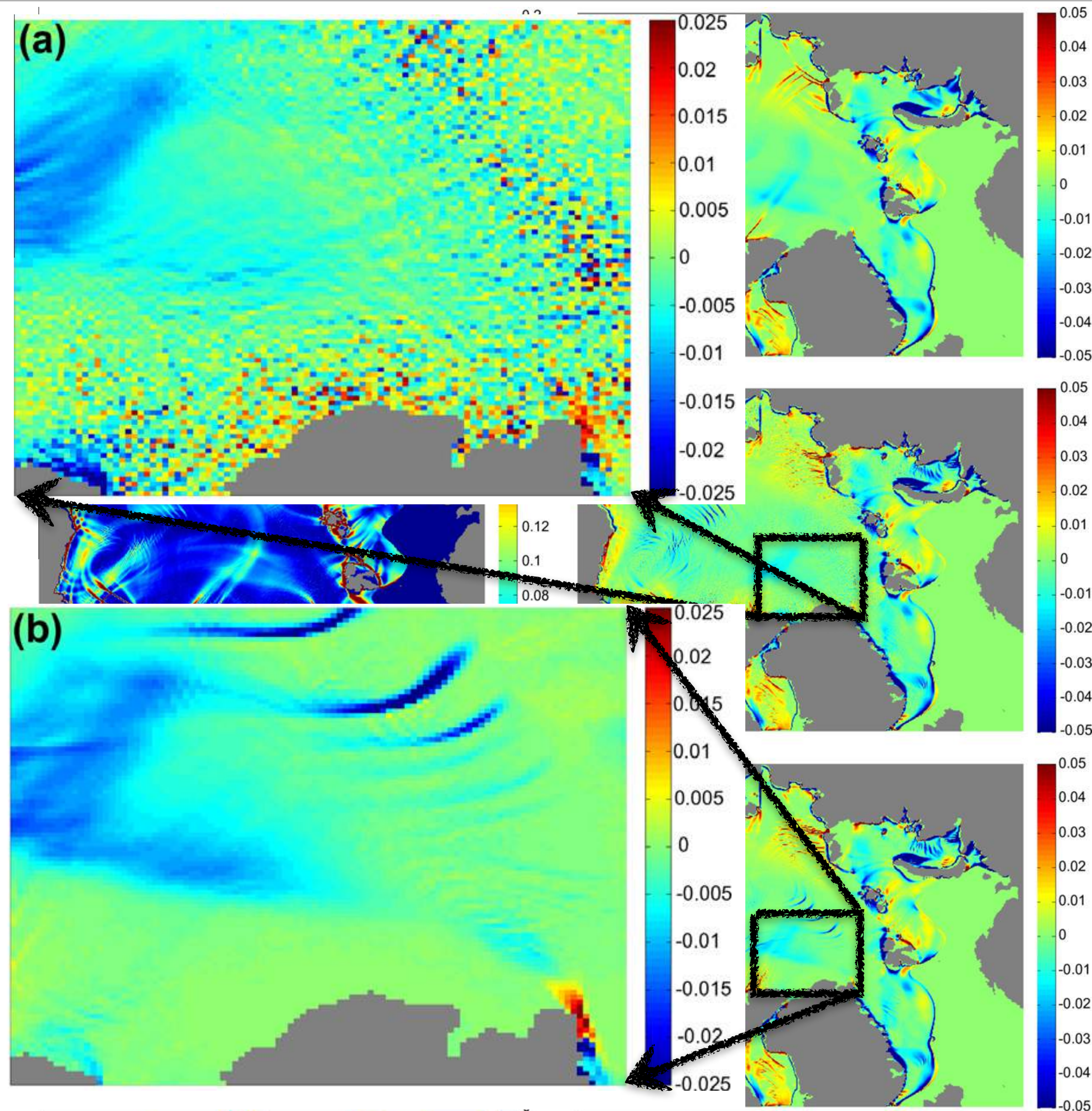


# issues with conventional EVP

reference

EVP, 120 sub-cycles

EVP, 1980 sub-cycles



Lemieux et al. (2012), shear and divergence (per day)



# New EVP equations

based on Lemieux et al. (2012), Bouillon et al. (2013), add “inertial-like” term to momentum equations

$$\begin{aligned}\boldsymbol{\sigma}^{p+1} - \boldsymbol{\sigma}^p &= \frac{1}{\alpha} \left( \boldsymbol{\sigma}(\mathbf{u}^p) - \boldsymbol{\sigma}^p \right), \\ \mathbf{u}^{p+1} - \mathbf{u}^p &= \frac{1}{\beta} \left( \frac{\Delta t}{m} \nabla \cdot \boldsymbol{\sigma}^{p+1} + \frac{\Delta t}{m} \mathbf{R}^{p+1/2} \right)\end{aligned}$$

# New EVP equations

New momentum equations

$$\sigma^{p+1} - \sigma^p = \frac{1}{\alpha} \left( \sigma(\mathbf{u}^p) - \sigma^p \right),$$
$$\mathbf{u}^{p+1} - \mathbf{u}^p = \frac{1}{\beta} \left( \frac{\Delta t}{m} \nabla \cdot \sigma^{p+1} + \frac{\Delta t}{m} \mathbf{R}^{p+1/2} + \mathbf{u}_n - \mathbf{u}^p \right)$$

with

$$\alpha\beta \gg \gamma = \frac{P}{2\Delta} \frac{(c\pi)^2}{A} \frac{\Delta t}{m}$$

from stability analysis (Kimmritz et al, 2015, 2016).

modified EVP:  $\alpha, \beta = \text{constant, order}(300)$

adaptive EVP:  $\alpha = \beta = (4\gamma)^{1/2}$



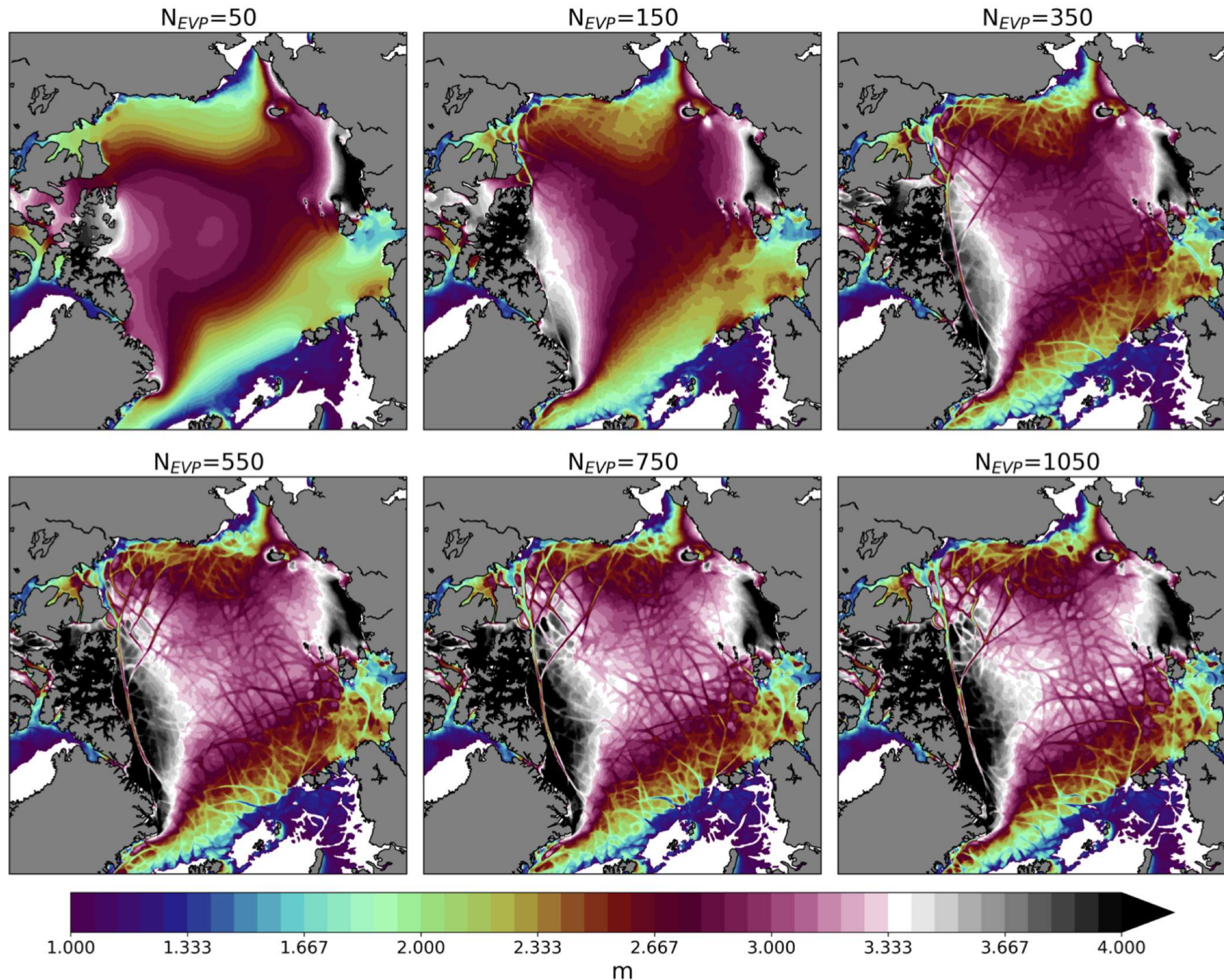
# high resolution simulations

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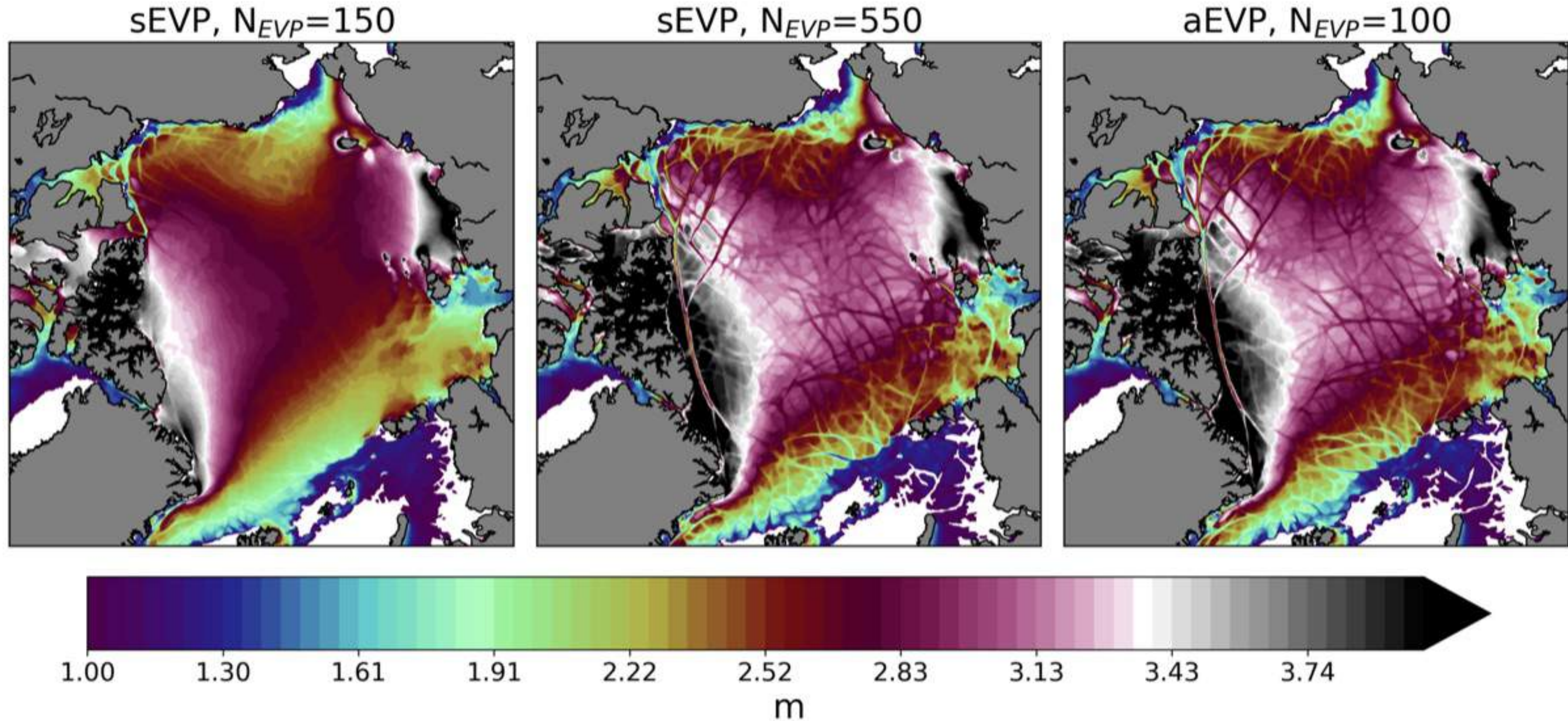
# EVP “convergence” (in FESOM)



Koldunov et al. (2019), JAMES  
~ 4 km

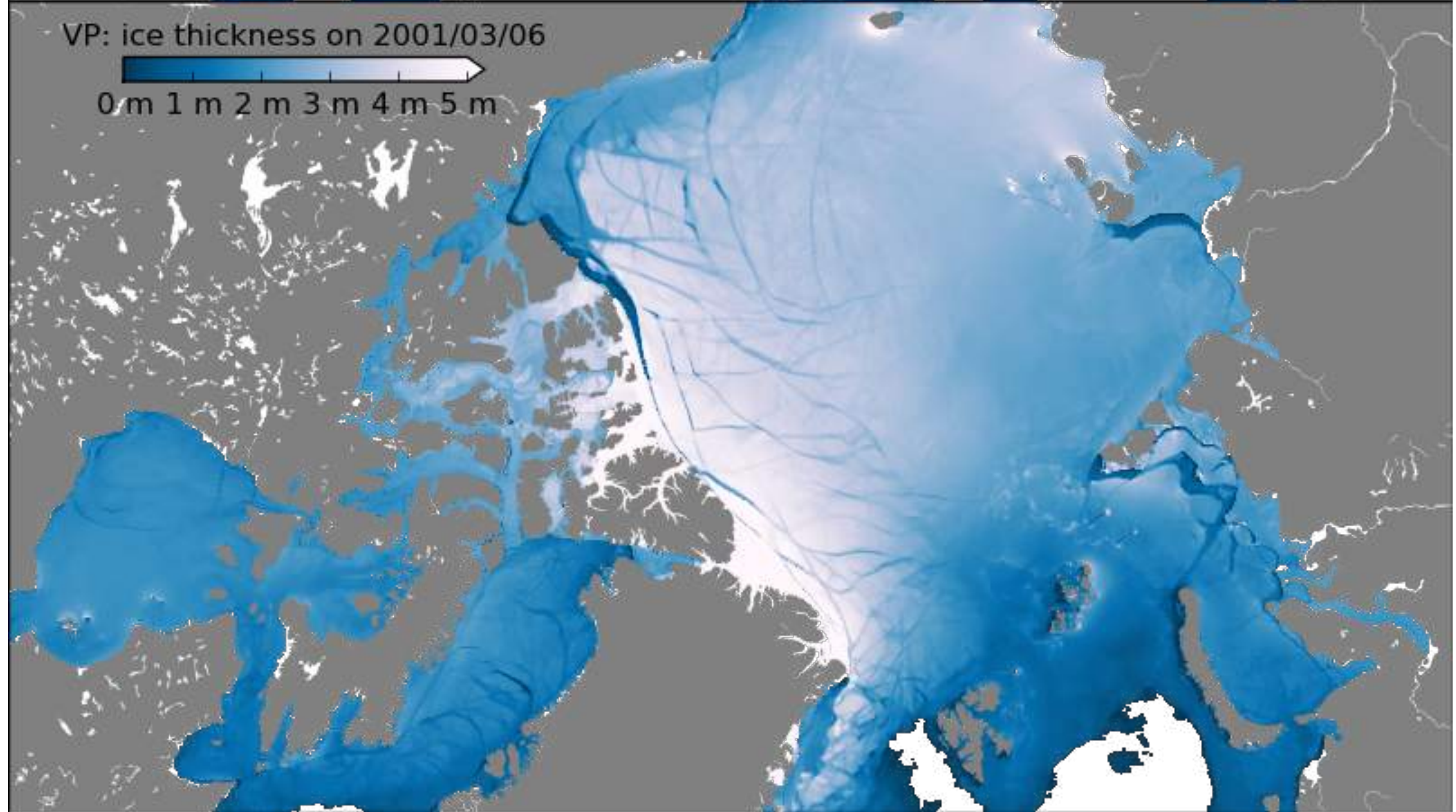


# EVP “convergence” (in FESOM)



Koldunov et al. (2019), JAMES, grid resolution  $\sim 4$  km





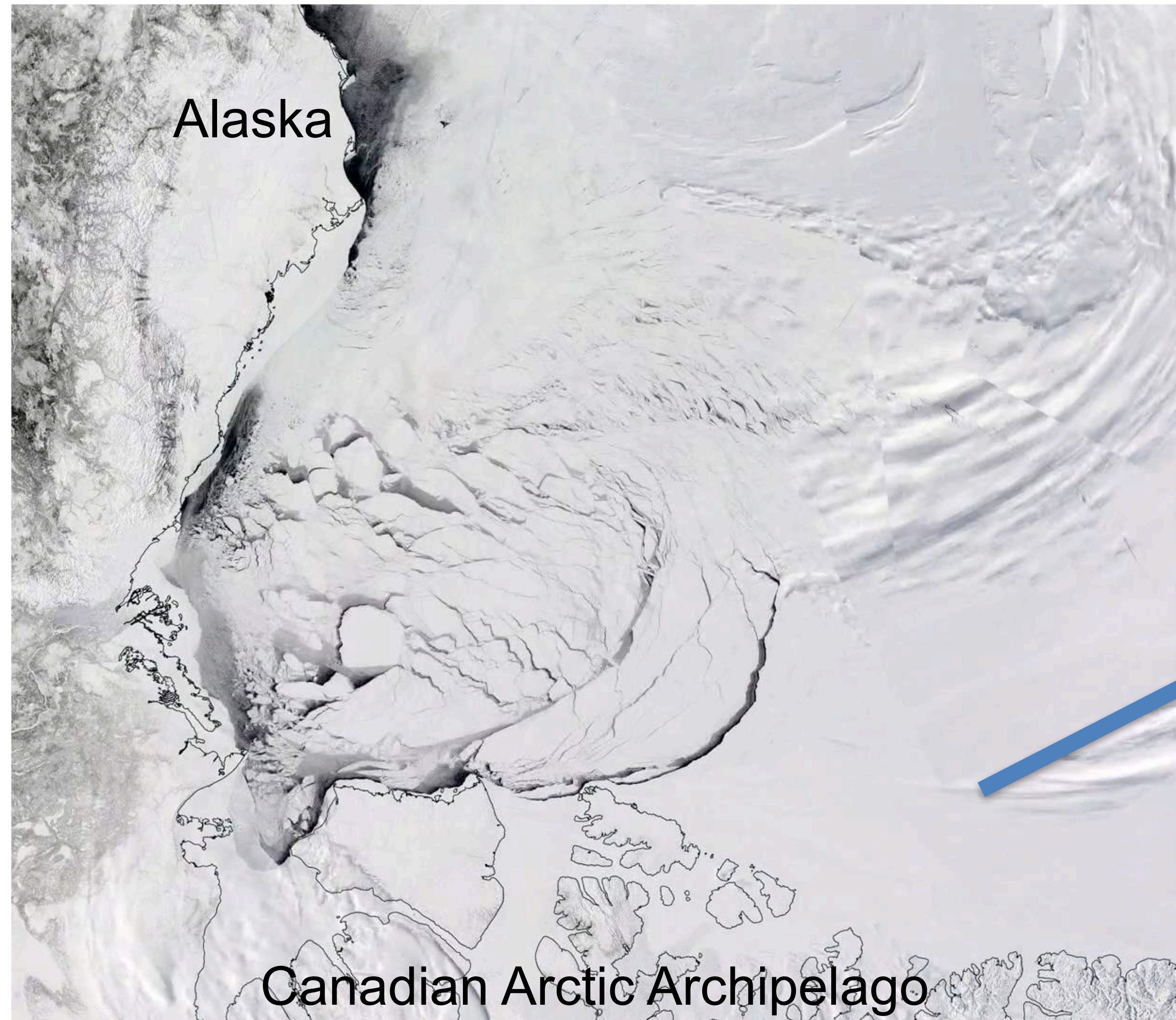
Convergence to  
VP solution:  
ice thickness (m)  
at 4.5 km grid  
spacing

$$\alpha\beta \gg \gamma = \zeta \frac{(c\pi)^2}{A_c} \frac{\Delta t}{m}$$

stability  
parameter  
depends on grid  
spacing and local  
ice viscosity



# sea ice dynamics from optical satellite images



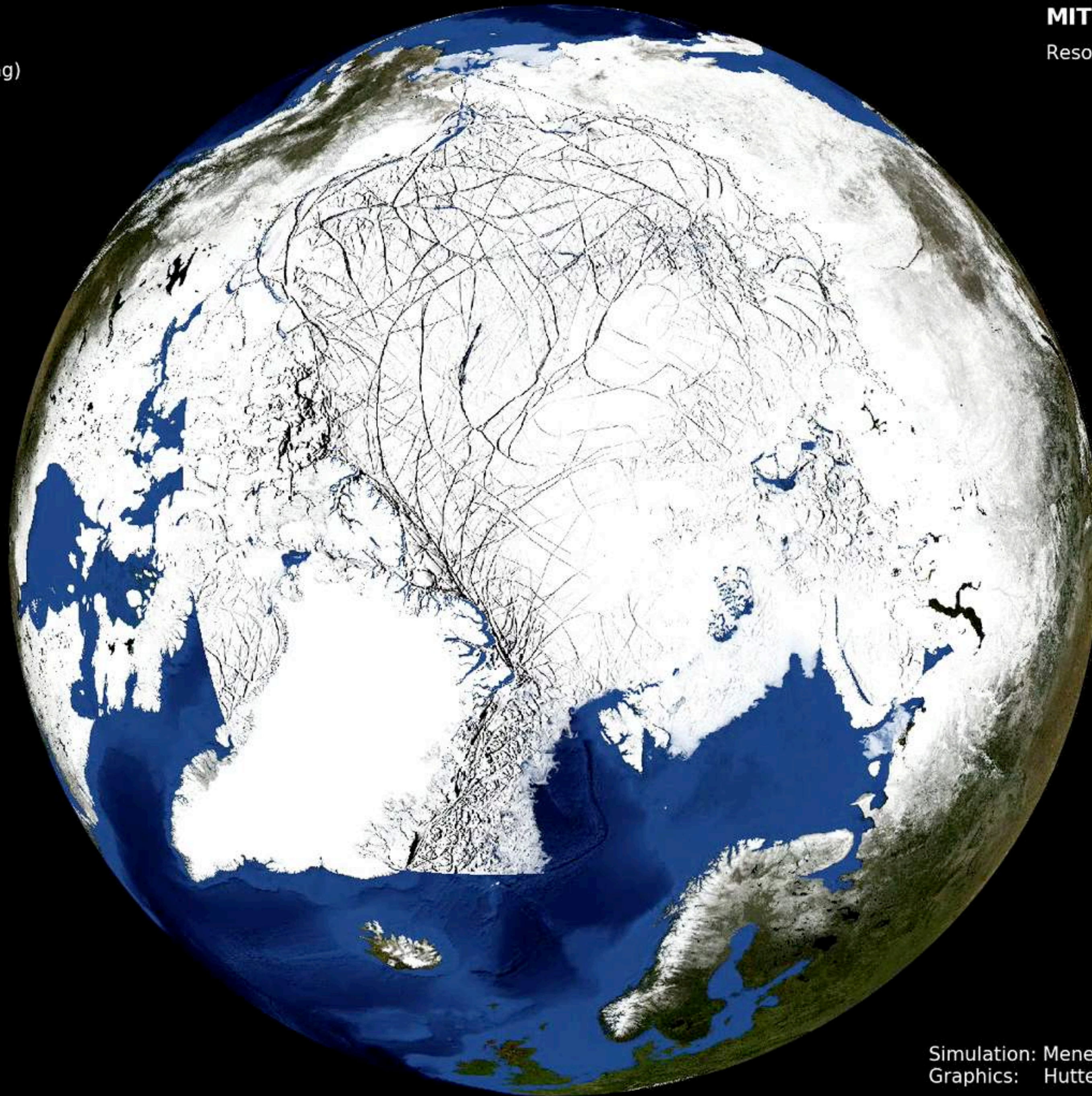
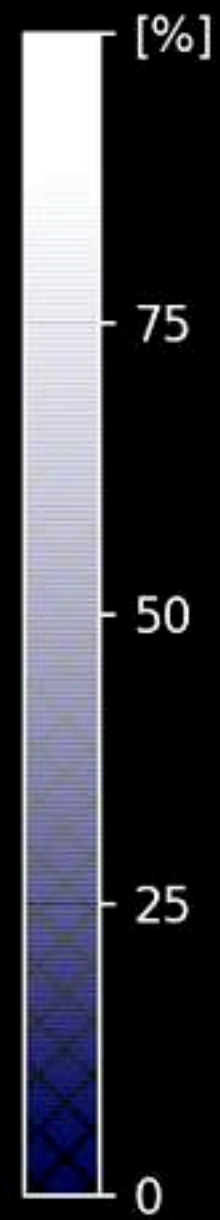


**Sea Ice**

Concentration (Opacity)  
and Thickness (Shadowing)

**MITgcm**

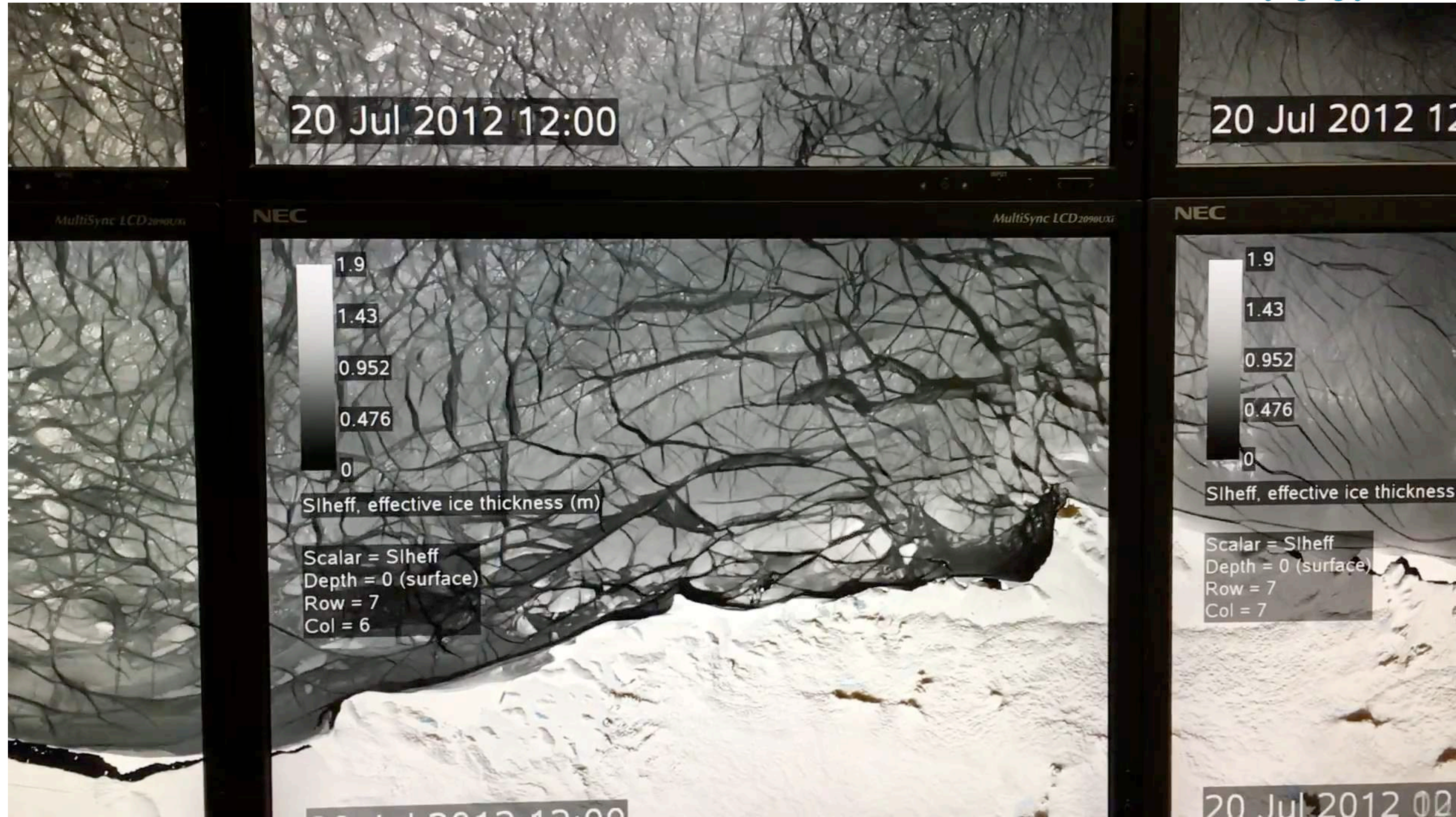
Resolution (1km)



2012/05/25

Simulation: Menemenlis (JPL)  
Graphics: Hutter (AWI)





Menemenlis, pers. comm



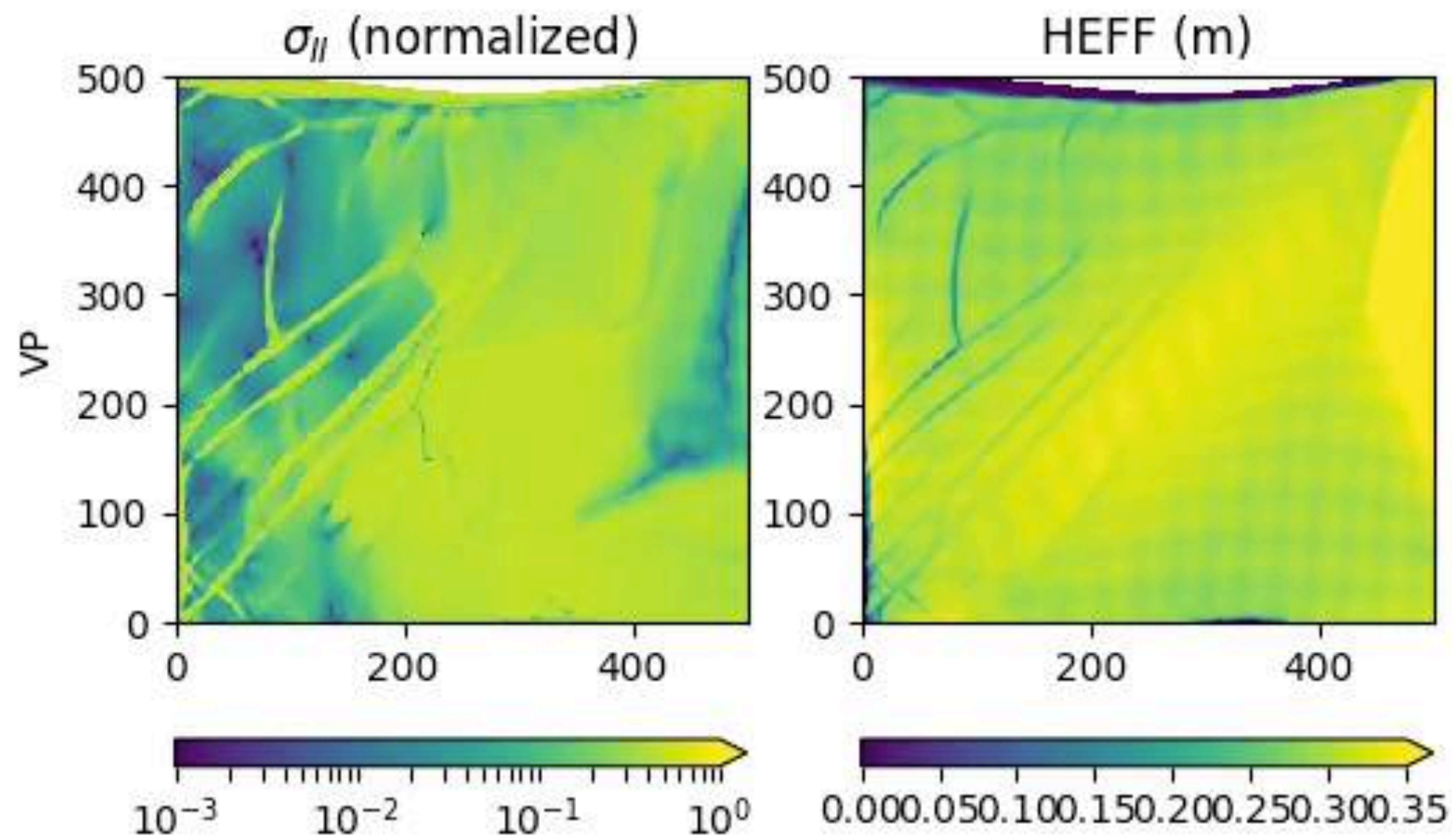
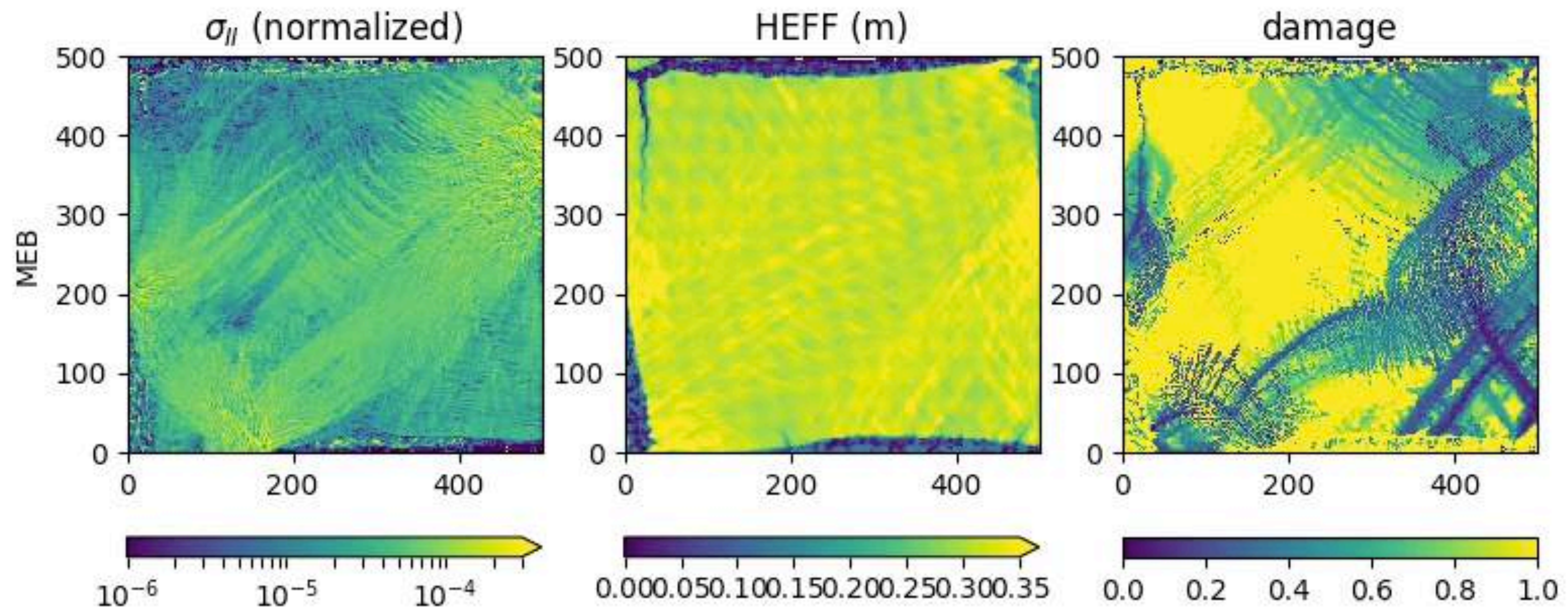
# Maxwell Elasto-Brittle rheology



- VP has been criticized for low intermittency and heterogeneity (Girard et al 2009, but Hutter et al 2018/2019 show opposite)
- Dansereau et al (2016):
$$\frac{1}{E} \frac{\partial \sigma}{\partial t} + \frac{1}{\lambda} \sigma = K : \dot{\epsilon}$$
  - new model variable: damage (actually integrity of sea ice), affects ice strength
  - Mohr-Coulomb law for failure (increases damage)  $(\tau = \mu\sigma + c)$
  - VP-viscosities are re-interpreted as constant coefficients; leads to a linear problem
- unclear: optimal solution strategy, computational cost (probably very high), stability, coupling to thermodynamics



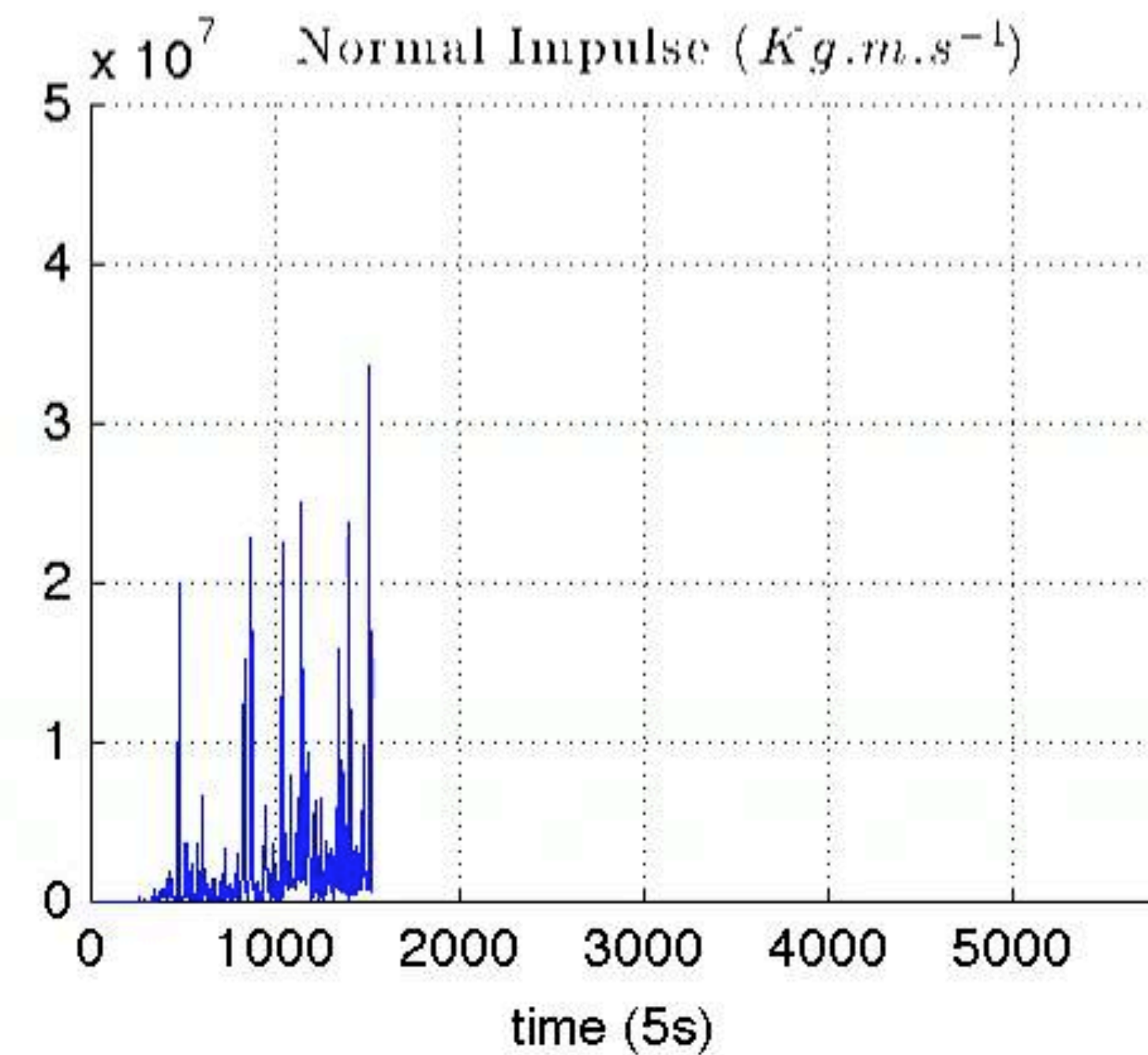
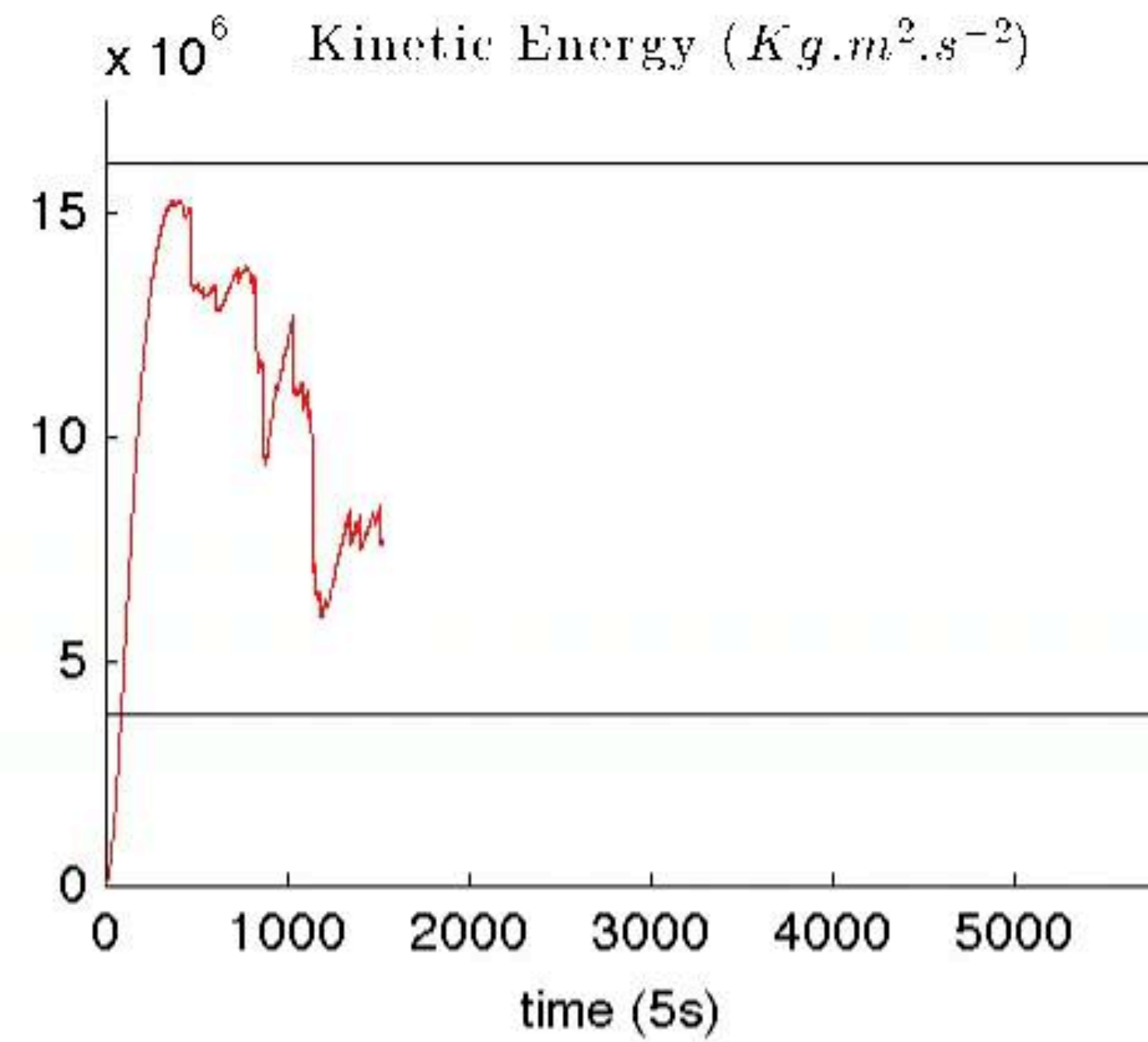
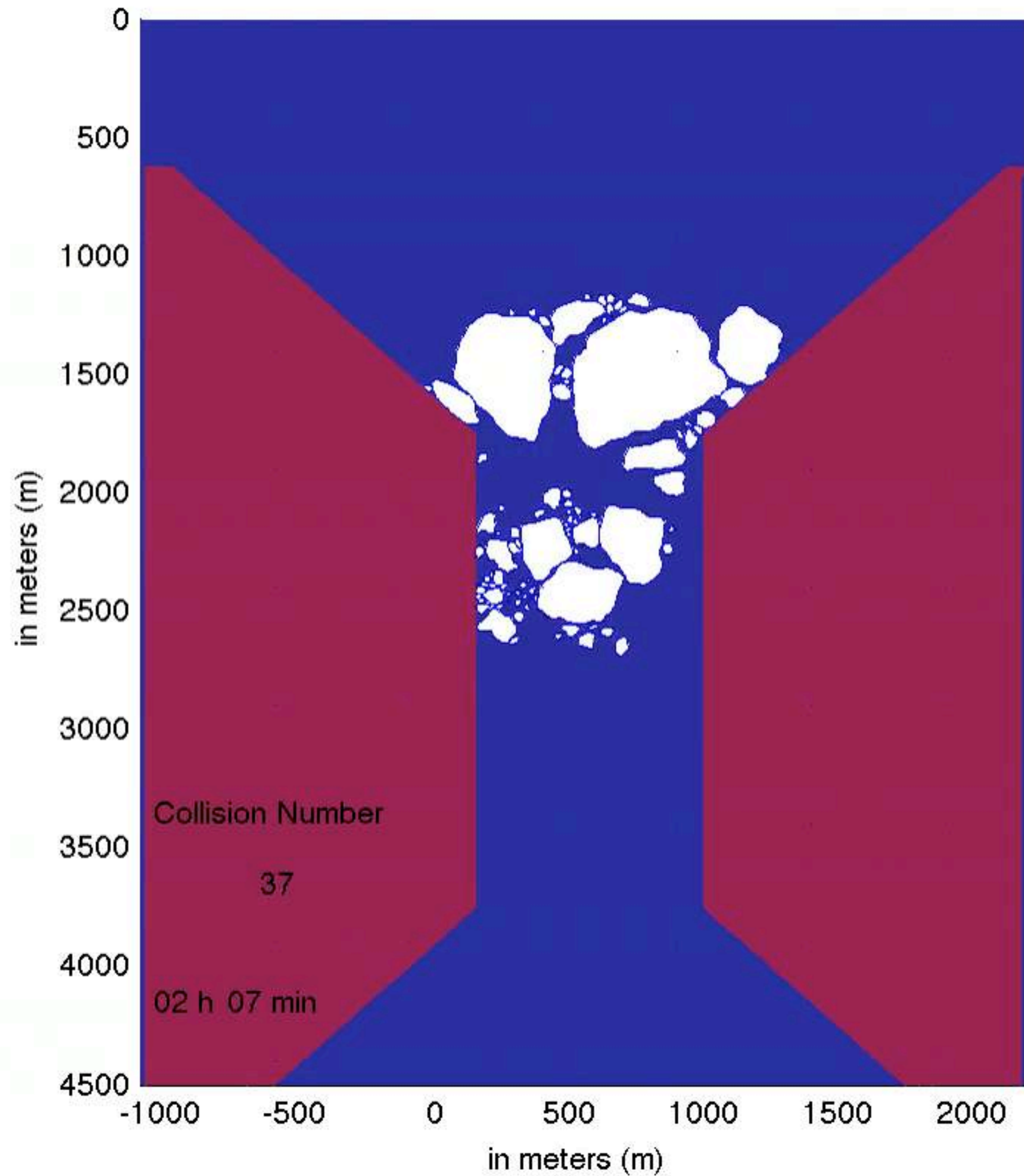
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**not sure if I should show this**



# Discrete Element Model: Rabatel et al 2015, JGR





- ice BGC affects attenuation (uptake) of shortwave radiation (albedo; modifies melt rate and availability to ocean), ocean BGC through “seeding” with biologically active material
- simple models for simple sea ice models, e.g. SIMBA (Castellani et al. 2017)
- multilayer models require more sophisticated sea ice models with positive definite vertical transport schemes, see documentation of “icepack” (column physics and biogeochemistry of CICE)
- numerous feedbacks need to be taken into account



# What's missing and where to go from here



- dynamics
  - explore continuity assumption at high resolution
  - new rheological approaches, anisotropy (EAP)
  - discrete element models for climate research?
  - surface and bottom stress (skin drag, form drag, ice roughness length, etc.)
  - porosity in ridges => ice strength parameterisations (Roberts et al. 2019)
- thermodynamics (most of this is in CICE/ICEPACK: <https://github.com/CICE-Consortium>)
  - multiple layers, vertical advection
  - melt pond parameterisations
  - snow parameterisations
  - biogeochemistry
- coupling to ocean and atmosphere
- ...



# Literature about sea ice modelling



- Reviews:
  - Hunke, E. C., W. H. Lipscomb, A. K. Turner (2010) *Sea-ice models for climate study: retrospective and new directions*. Journal of Glaciology, Vol. 56, No. 200, <https://www.igsoc.org/journal/56/200/j10j186.pdf>
  - Lemieux, J.-F., S. Bouillon, F. Dupont, G. Flato, M. Losch, P. Rampal, B. Tremblay, M. Vancoppenolle, and T. Williams (2017). *Sea ice physics and modelling*. In T. Carrieres, M. Buehner, J.-F. Lemieux, and L. T. Pedersen, eds., *Sea Ice Analysis and Forecasting, Towards an Increased Reliance on Automated Prediction Systems*, pages 51–108. Cambridge University Press, Cambridge, United Kingdom; New York, NY, October 2017. ISBN 978-1-108-41742-6. doi: 10.1017/9781108277600. URL [www.cambridge.org/9781108417426](http://www.cambridge.org/9781108417426).
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